



# Component Substitution through Dynamic Reconfigurations

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# Outline

Running example and motivations

Architectural model with reconfigurations

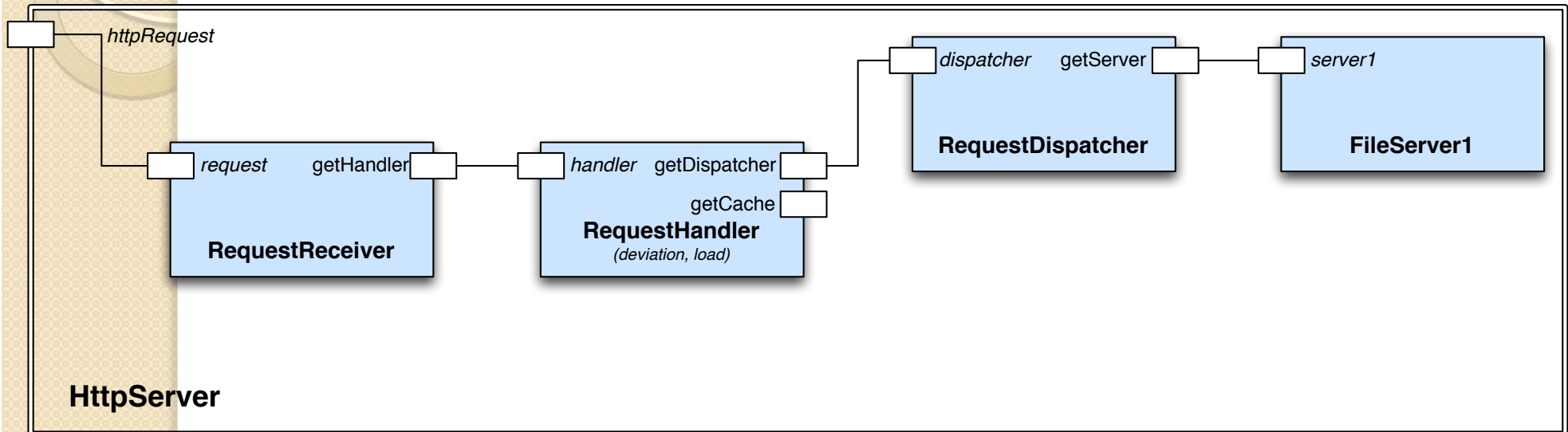
Reconfigurations by component substitution

Substitutability-based simulation, at runtime

Implementation

Conclusion

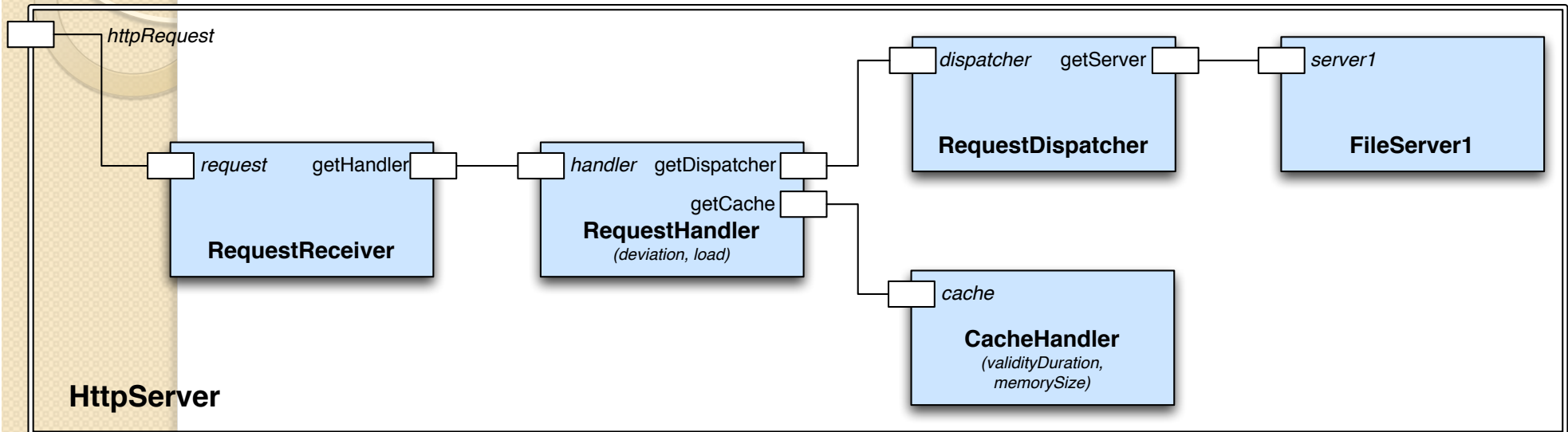
# Running example: HTTP Server



## Dynamic reconfigurations:

- AddCacheHandler / RemoveCacheHandler
- AddFileServer / RemoveFileServer

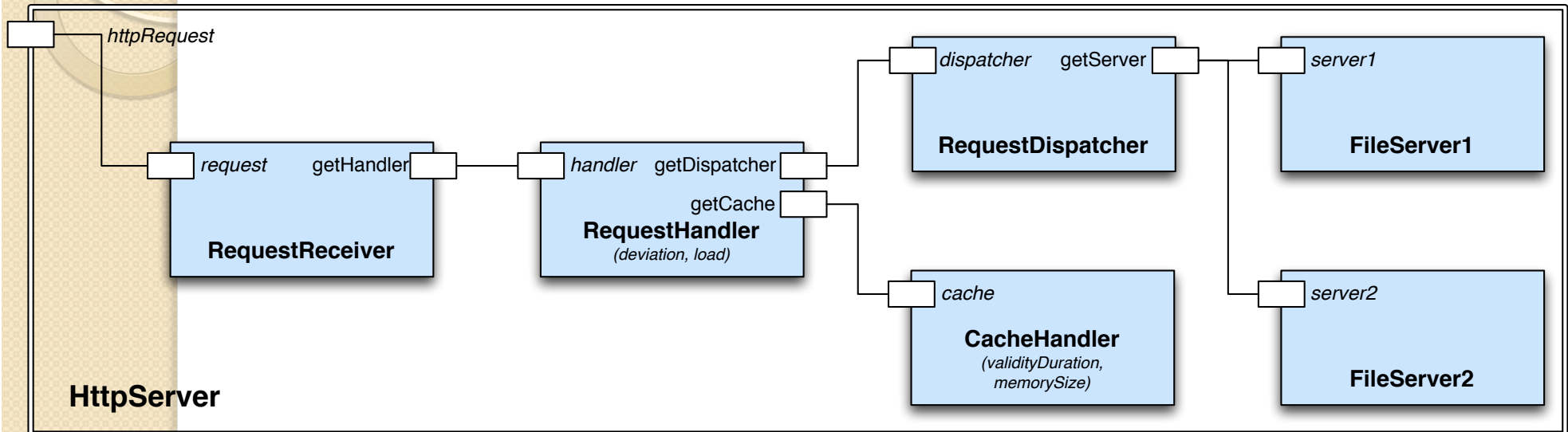
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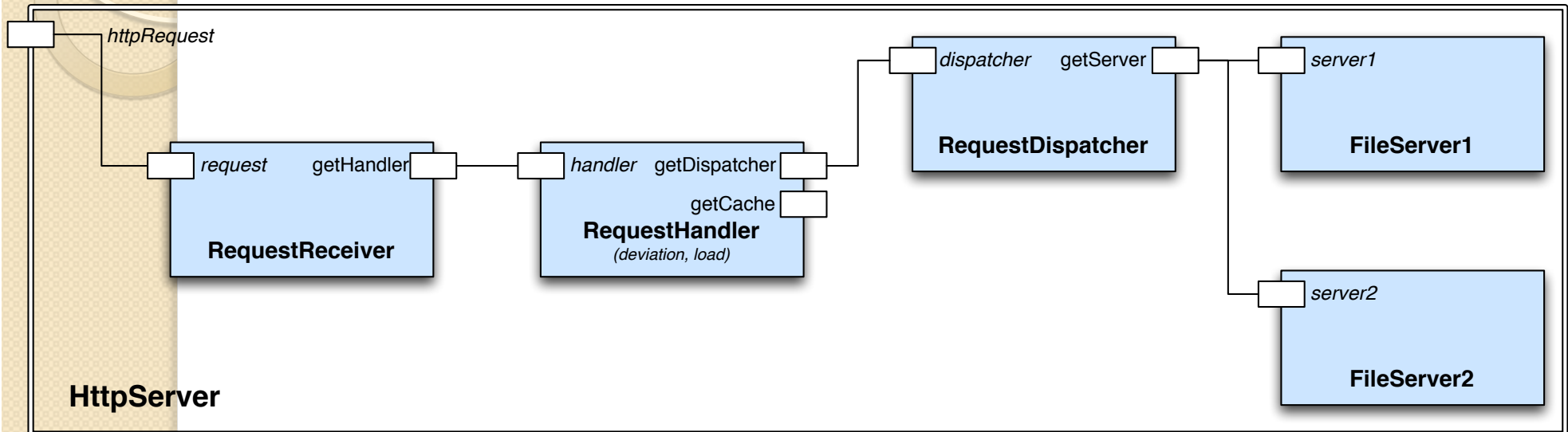
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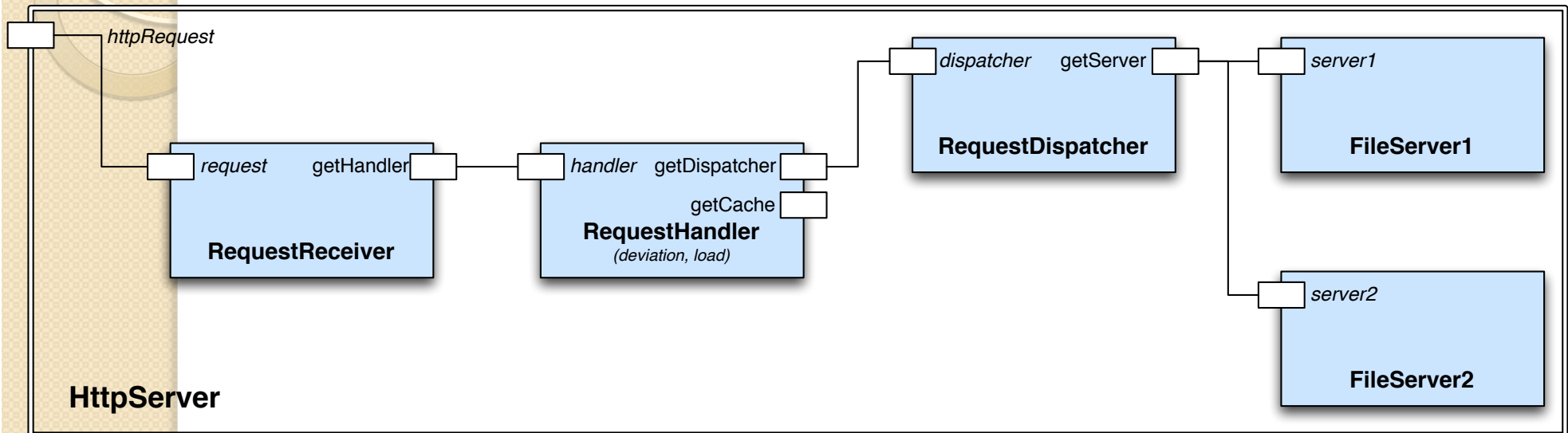
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- AddFileServer / RemoveFileServer

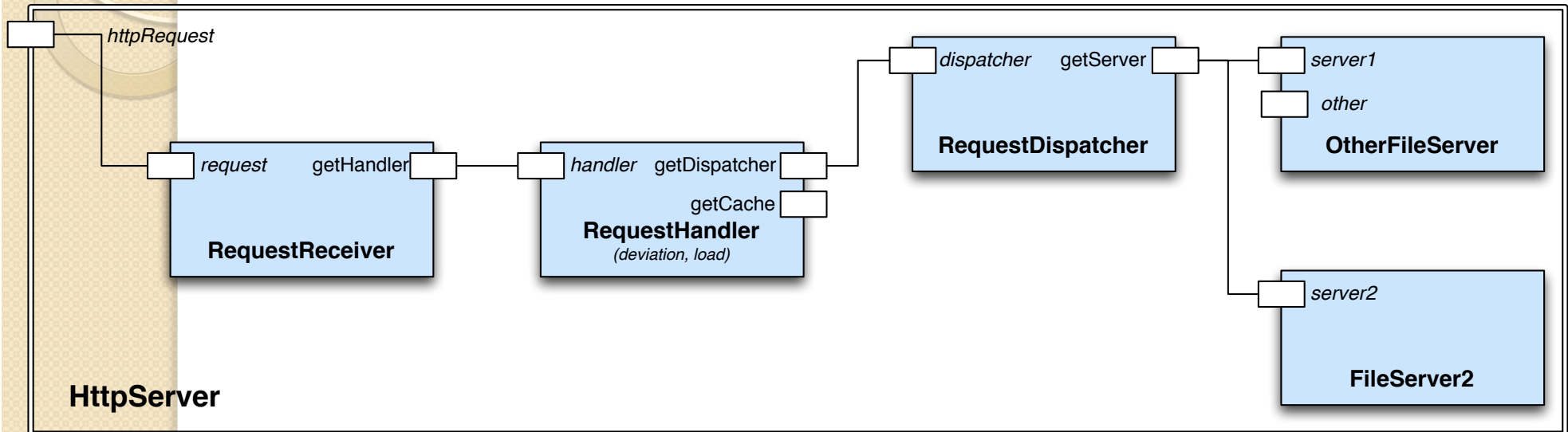
# Running example: HTTP Server



## Reconfiguration by substitution:

- Replace **RequestHandler** by **RequestHandler\_R**
- Replace **FileServer1** by **AnotherFileServer**

# Running example : HTTP Server

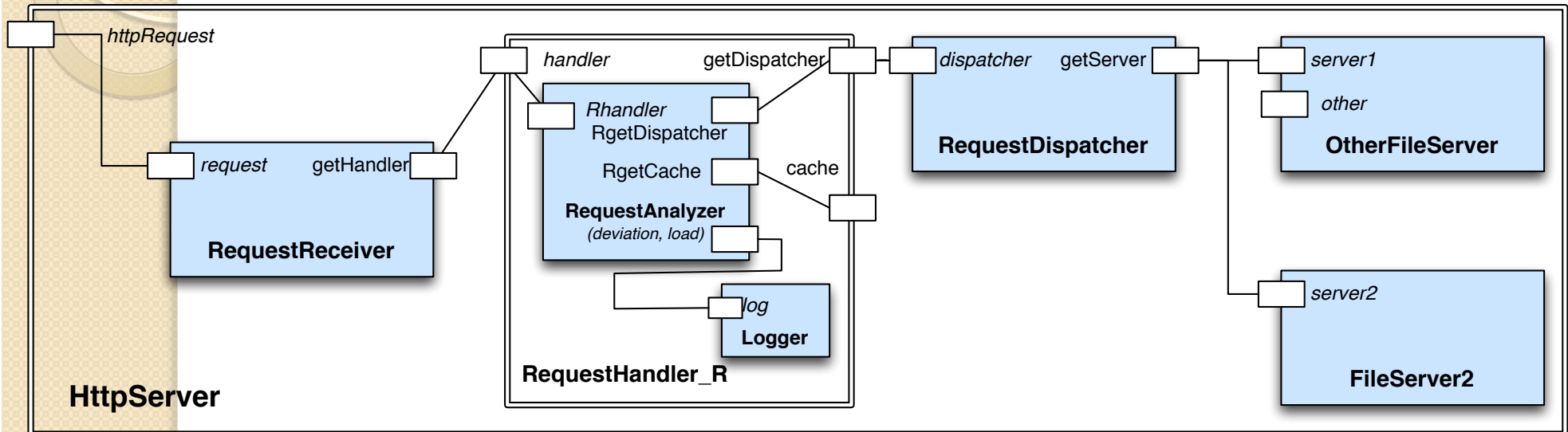


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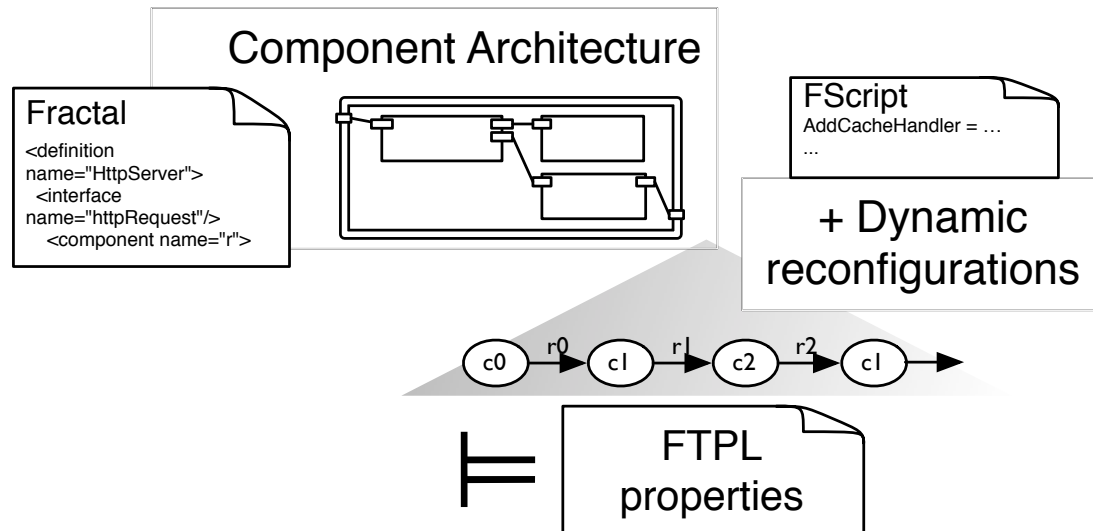
# Running example: HTTP Server



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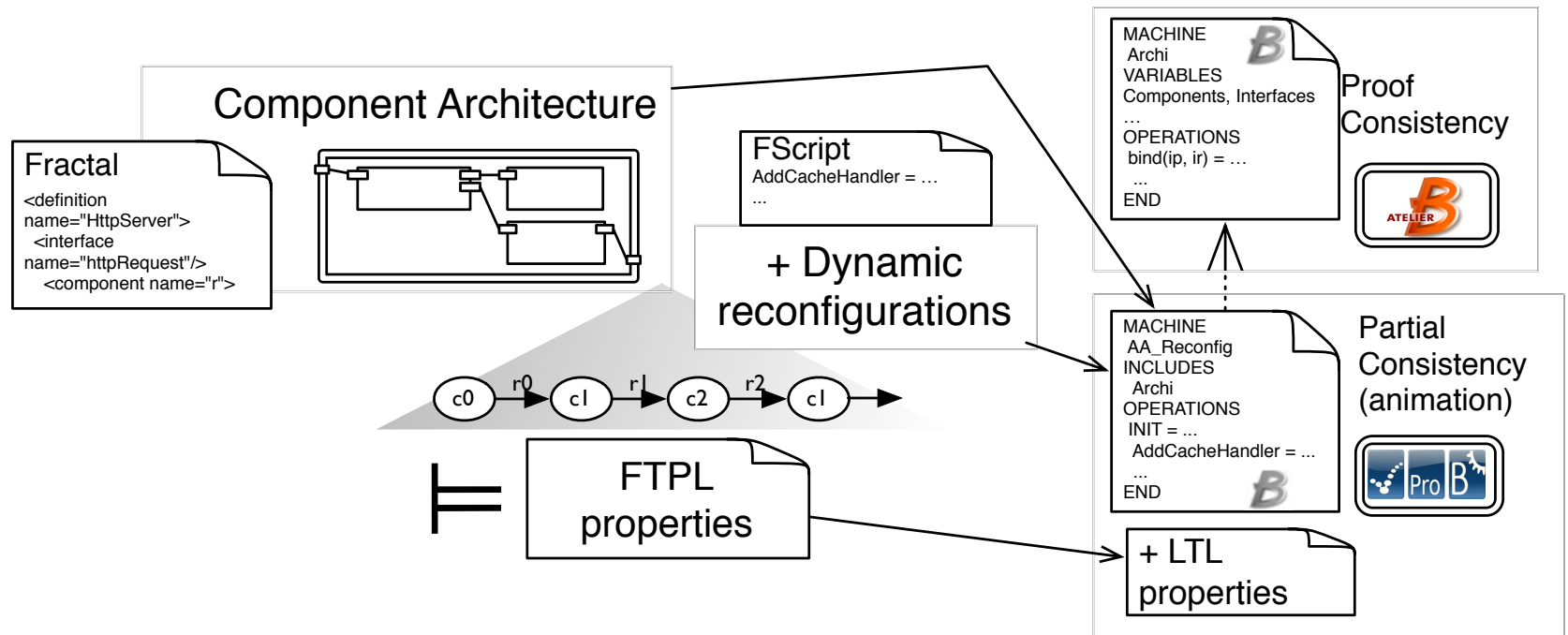
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# Previous works



J. Dormoy, O. Kouchnarenko & A. Lanoix  
*Using Temporal Logic for Dynamic Reconfigurations of Components.*  
FACS 2010

# Previous works

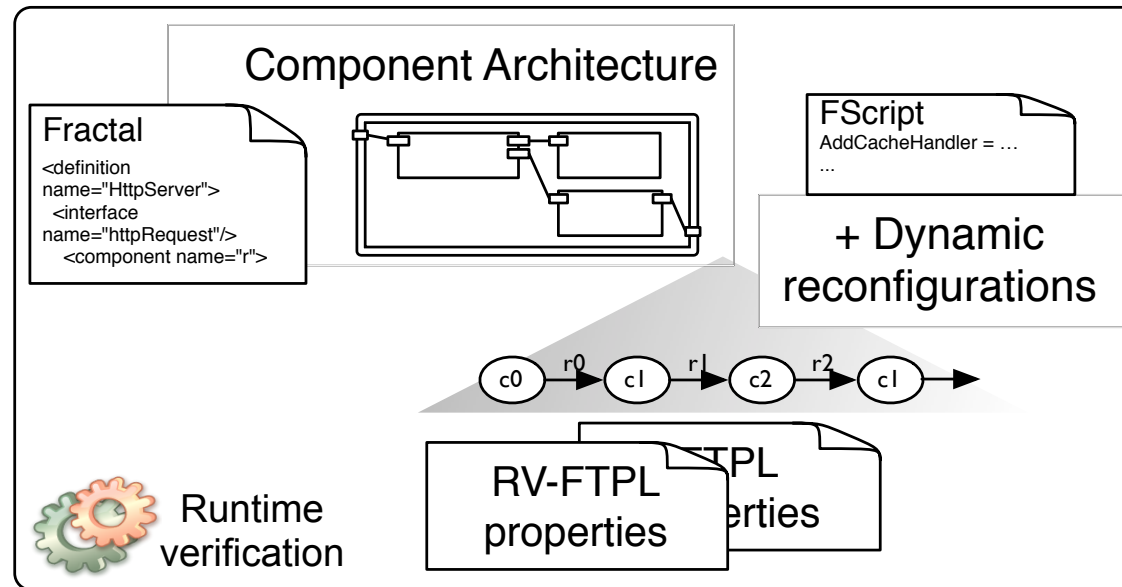


A.Lanoix, J.Dormoy & O.Kouchnarenko

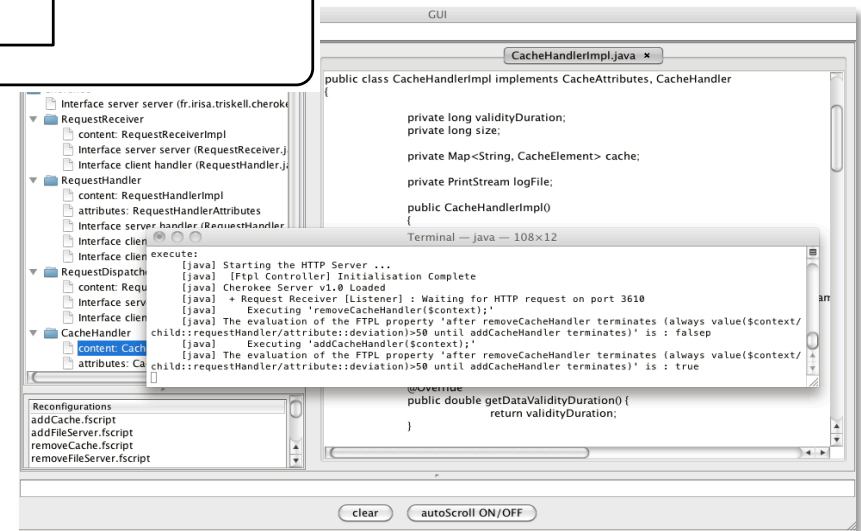
*Combining Proof and Model-checking to Validate Reconfigurable Architectures.*

FESCA 2011

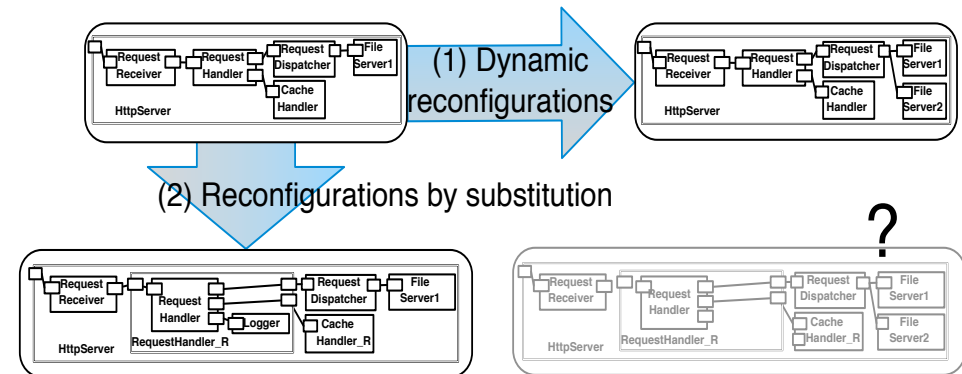
# Previous works



J. Dormoy, O. Kouchnarenko & A. Lanoix  
*Runtime Verification of Temporal Patterns for  
Dynamic Reconfigurations of Components.*  
FACS 2011



# Motivations



- *Needs*

- Validate component architectures evolution through reconfigurations
- Combine different kinds of reconfigurations
  - **Dynamic reconfigurations (1)**
  - **Reconfigurations by substitution (2)**

- *Proposals*

- Define **Substitutability Constraints**
- Integrate them into a **substitutability-based simulation**
  - Propose a semi-algorithm to check it on the fly



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Architectural model with reconfigurations

Reconfigurations by component substitution

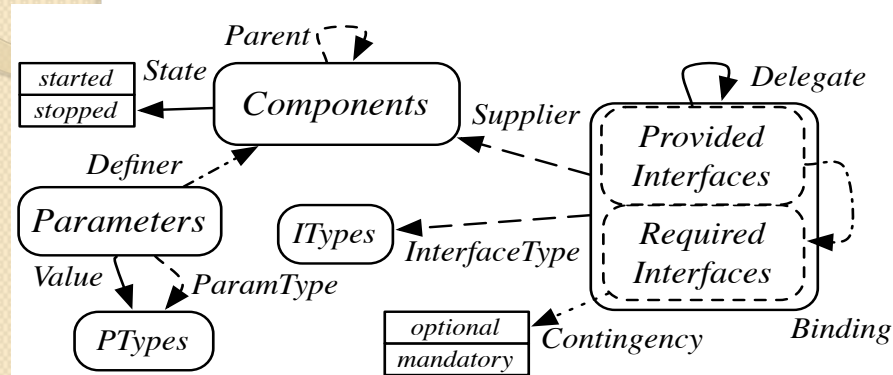
Substitutability-based simulation, at runtime

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# Architectural reconfiguration model

- **Graph-based representation** of the component architecture

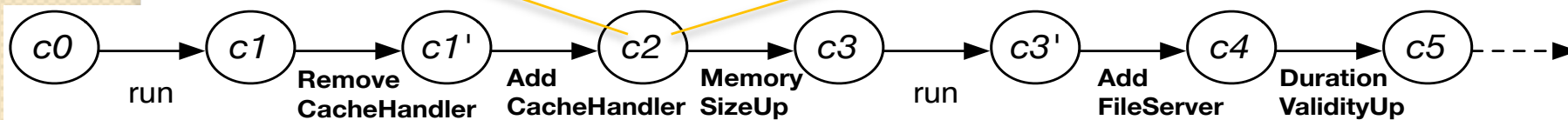
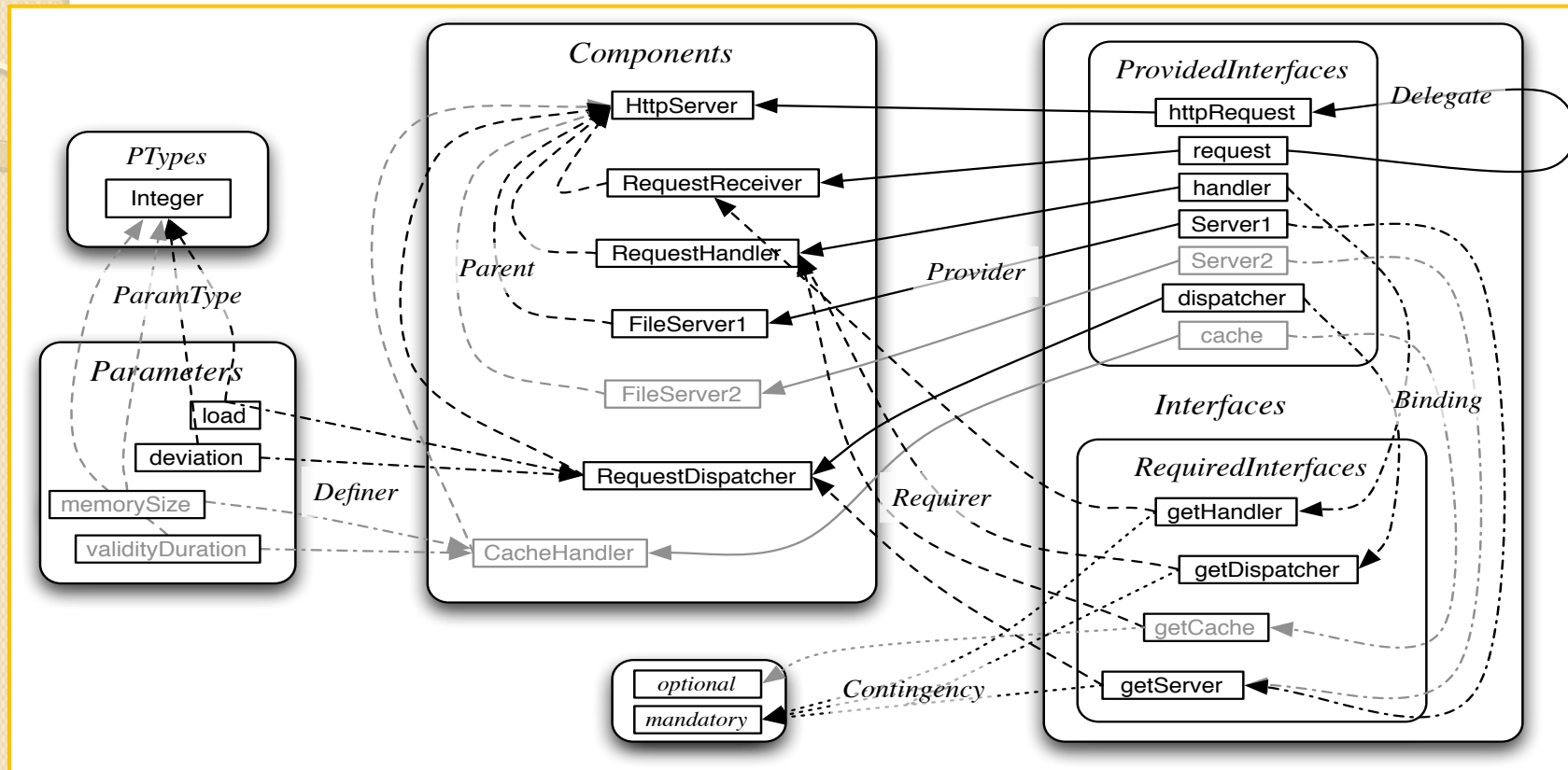


Configurations =  
architectural elements  
+ relations

- **Consistent configurations**
  - Configurations respect the Consistency Constraints CC
- **Dynamic reconfigurations** = graph transformations
  - add/delete components
  - bind/unbind interfaces
  - change value of parameters

} combination  
of them

# Architectural reconfiguration model







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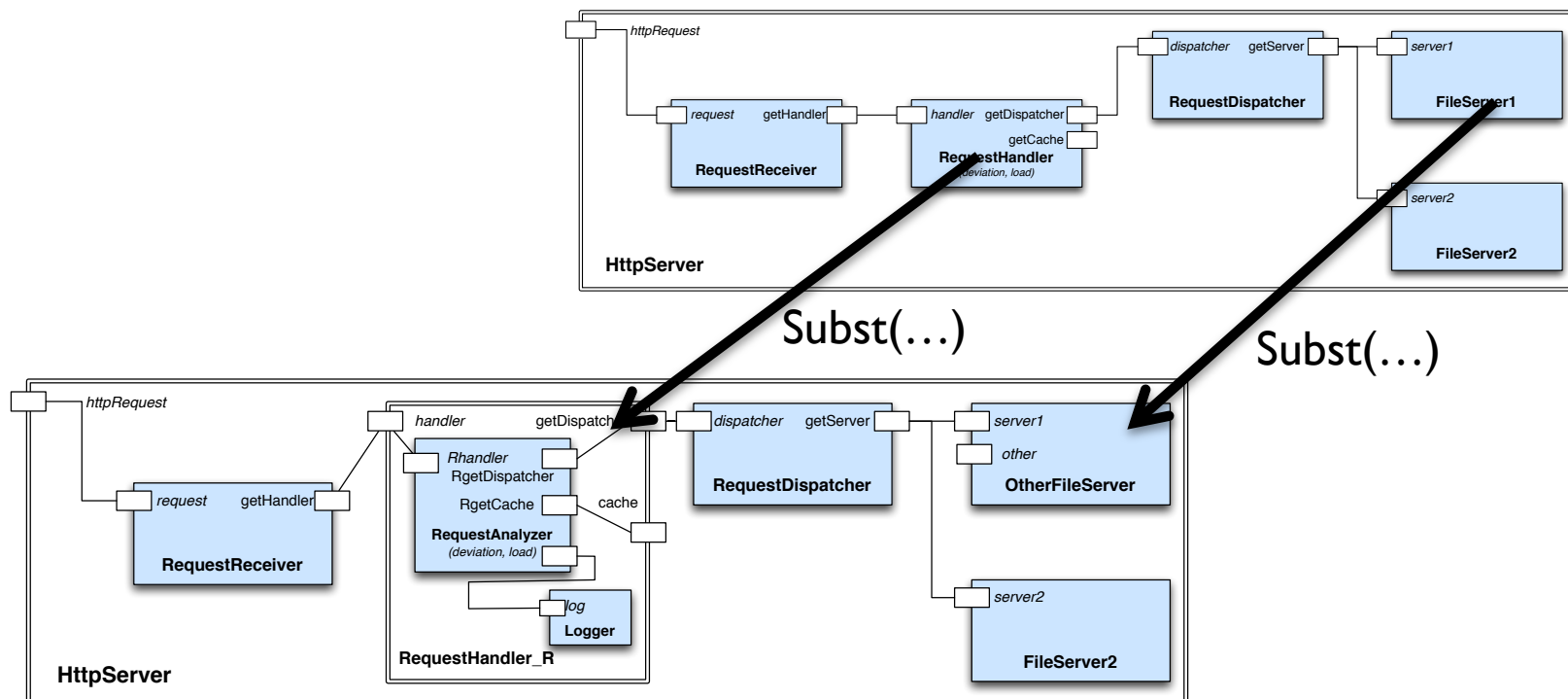
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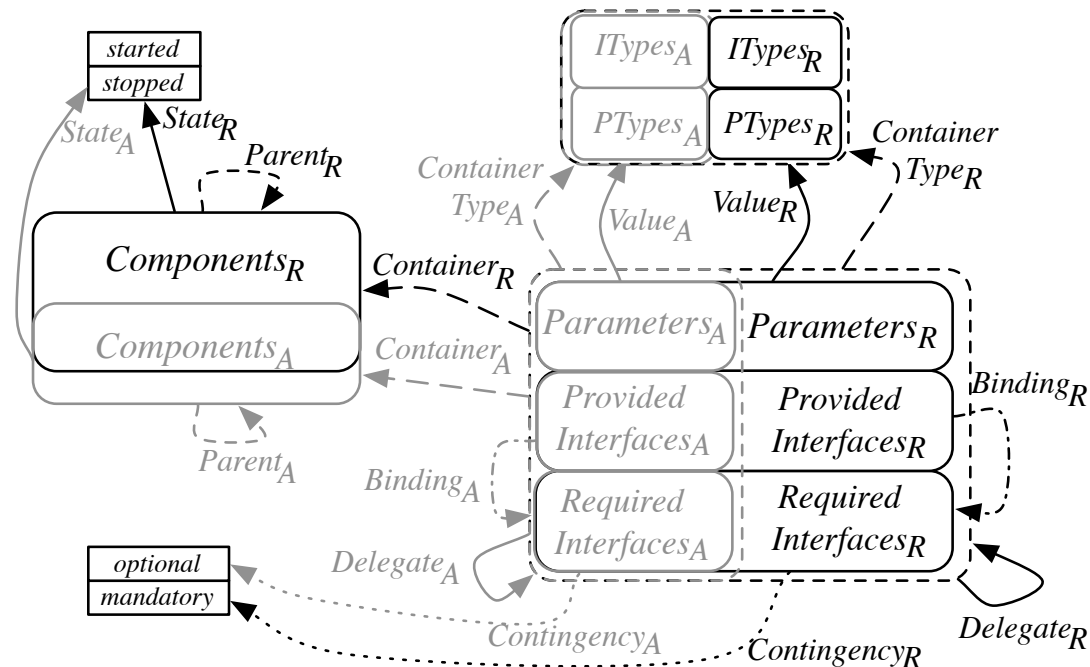
# Reconfigurations by component substitution

- Two kinds of component substitutions:
  - **new version** of the component
  - **composite component** encapsulates new sub-components



# Reconfigurations by component substitution

- Component **structural substitution** vs. Component encapsulation
  - Substituted components supply the **same interfaces** as before



→ (Structural) **substitutability constraints**

# Some substitutability constraints

- "the old components remain unchanged" [5/21]

$$\forall c \in \text{Components}_A \cap \text{Components}_R, \left( \begin{array}{l} \text{Container}_A(x) = c \\ \Rightarrow \text{Container}_R(x) = c \end{array} \right)$$

$$\forall x \in \text{Interfaces}_A \cup \text{Parameters}_A$$

- "an old component completely disappears only if it is substituted by a new version of itself" [7/21]

$$\forall c_A \in \text{Components}_A \setminus \text{Components}_R \Rightarrow$$

$$\left( \exists c_R \in \text{Components}_R \setminus \text{Components}_A. (\text{Subst}(c_A) = c_R) \right)$$

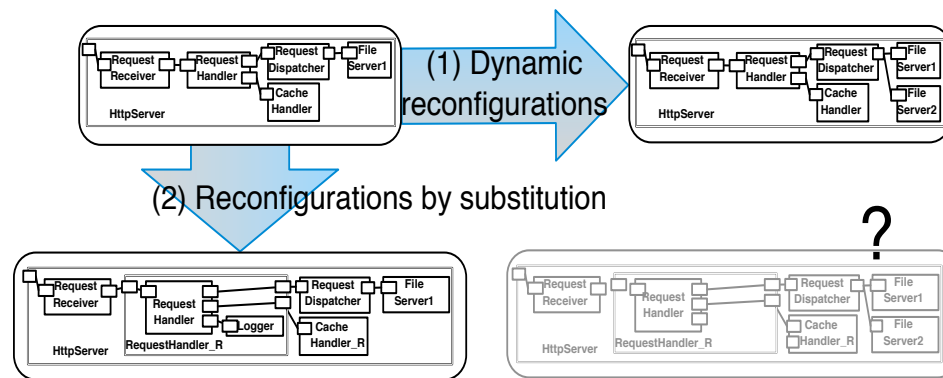
- "the newly introduced components must be subcomponents of some substituted components" [12/21]

$$\forall c_R \in \text{Components}_R \setminus \text{Components}_A \left( \text{Subst}(c_A) \neq c_R \Rightarrow \right)$$

$$\forall c_A \in \text{Components}_A \setminus \text{Components}_R \left( \exists c'_R \in \text{Components}_R \setminus \text{Components}_A. ((c_R, c'_R) \in \text{Parent}_R) \right)$$

# Combining component substitution with dynamic reconfigurations

- **Newly** substituted components introduce **new** dynamic reconfigurations



- How to make new reconfigurations **preserve** the old reconfiguration sequences?
- **→ Substitutability-based simulation**
  - a kind of weak simulation [Milner-Park]



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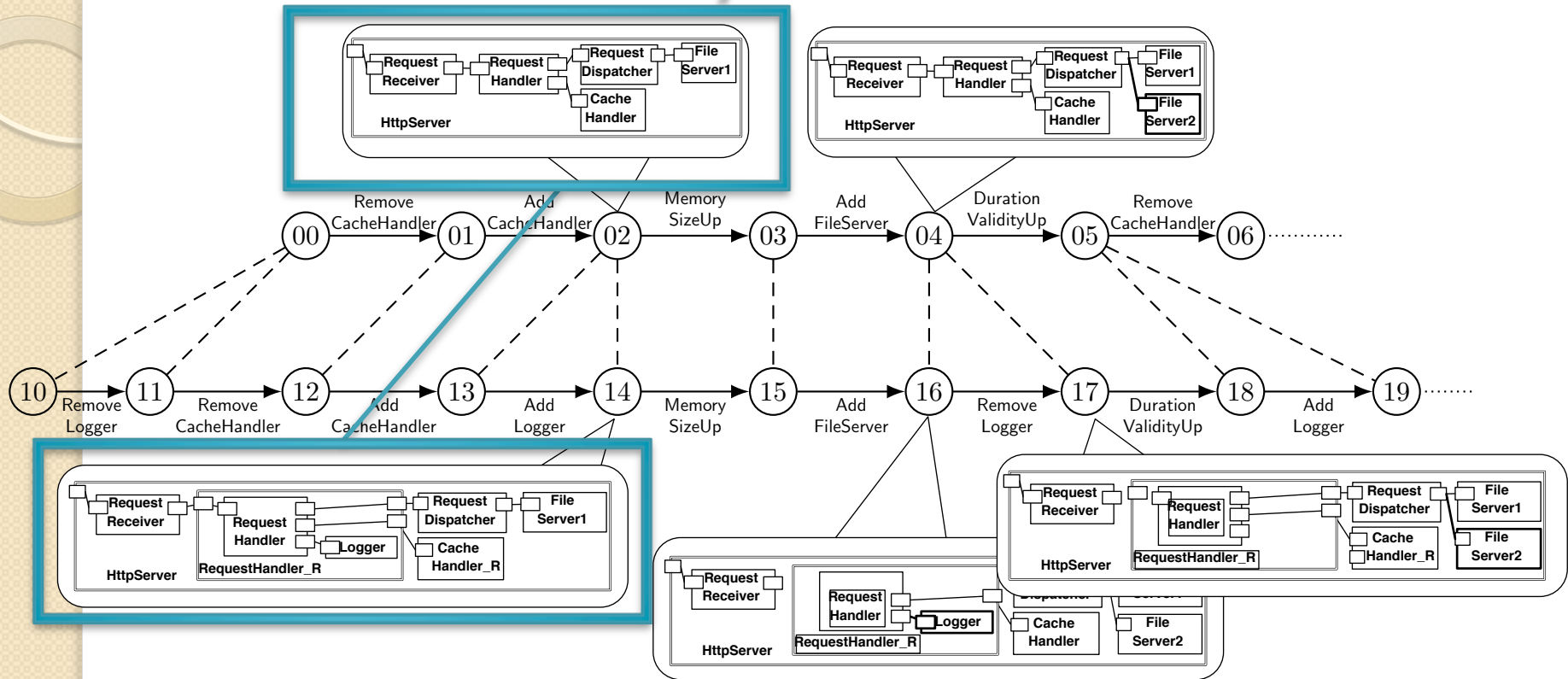
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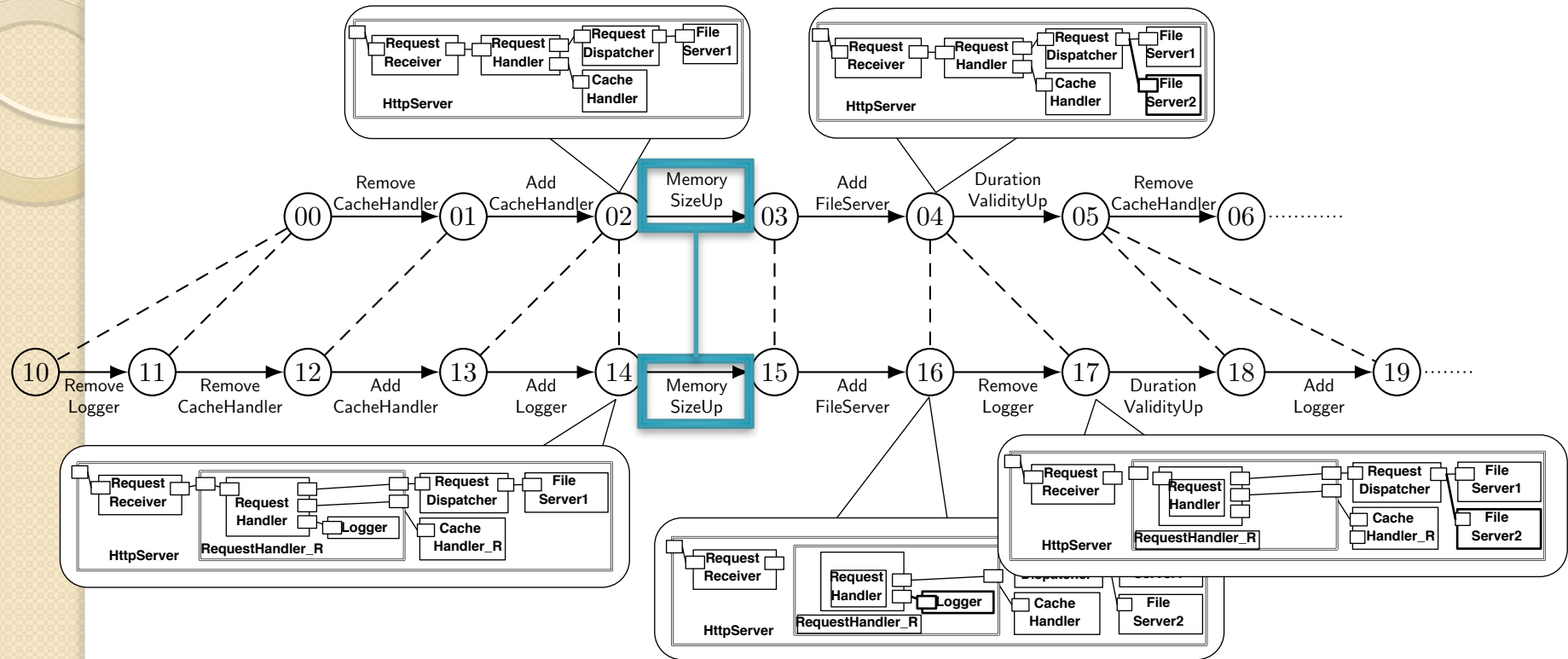
Conclusion

# Substitutability-based simulation



## I. Substitutability constraints

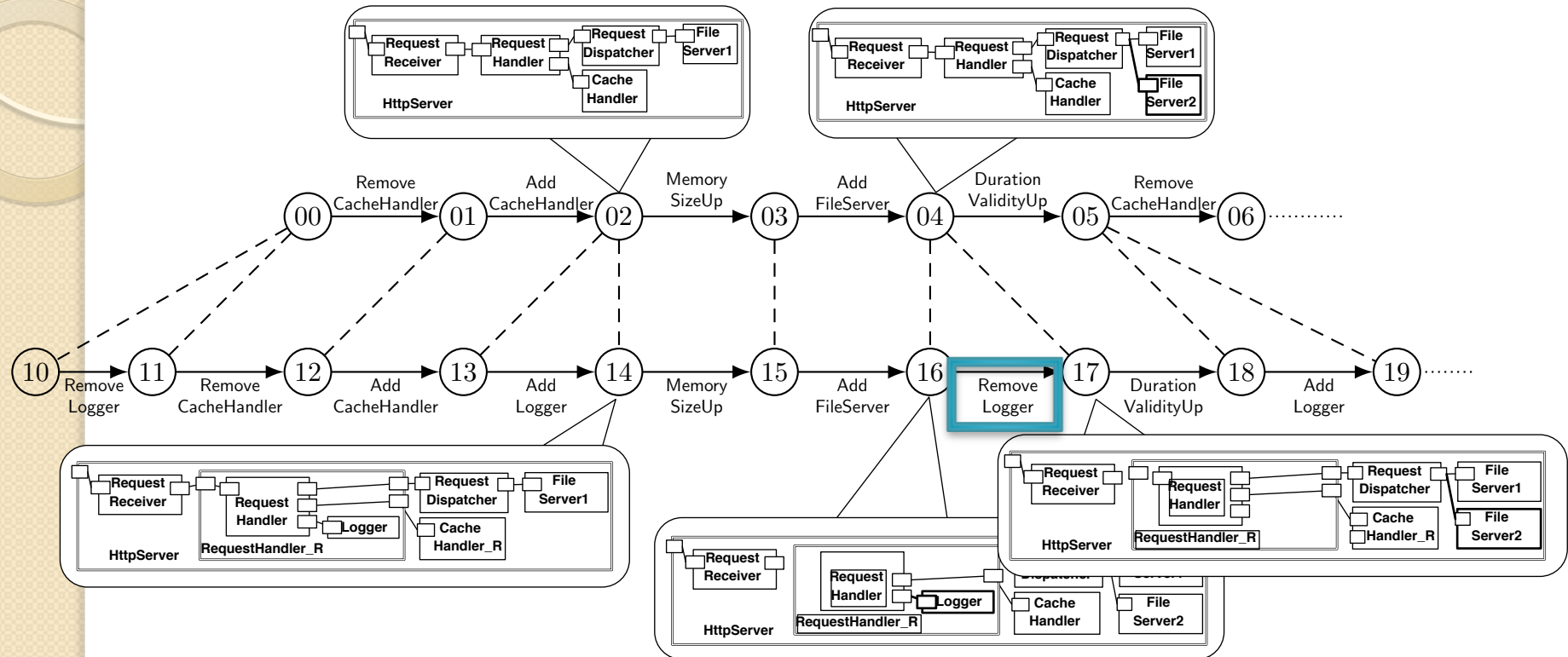
# Substitutability-based simulation



1. Substitutability constraints
2. **Strict reconfiguration simulation**

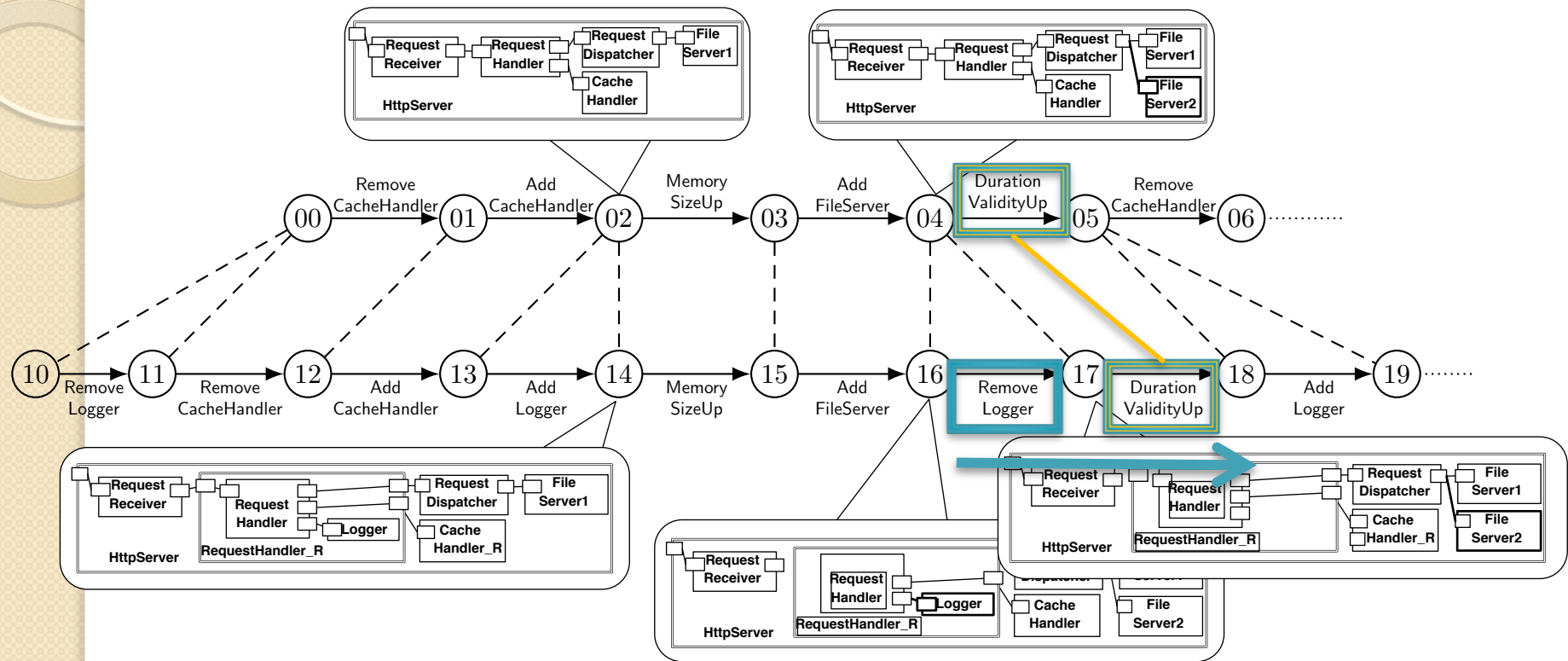


# Substitutability-based simulation



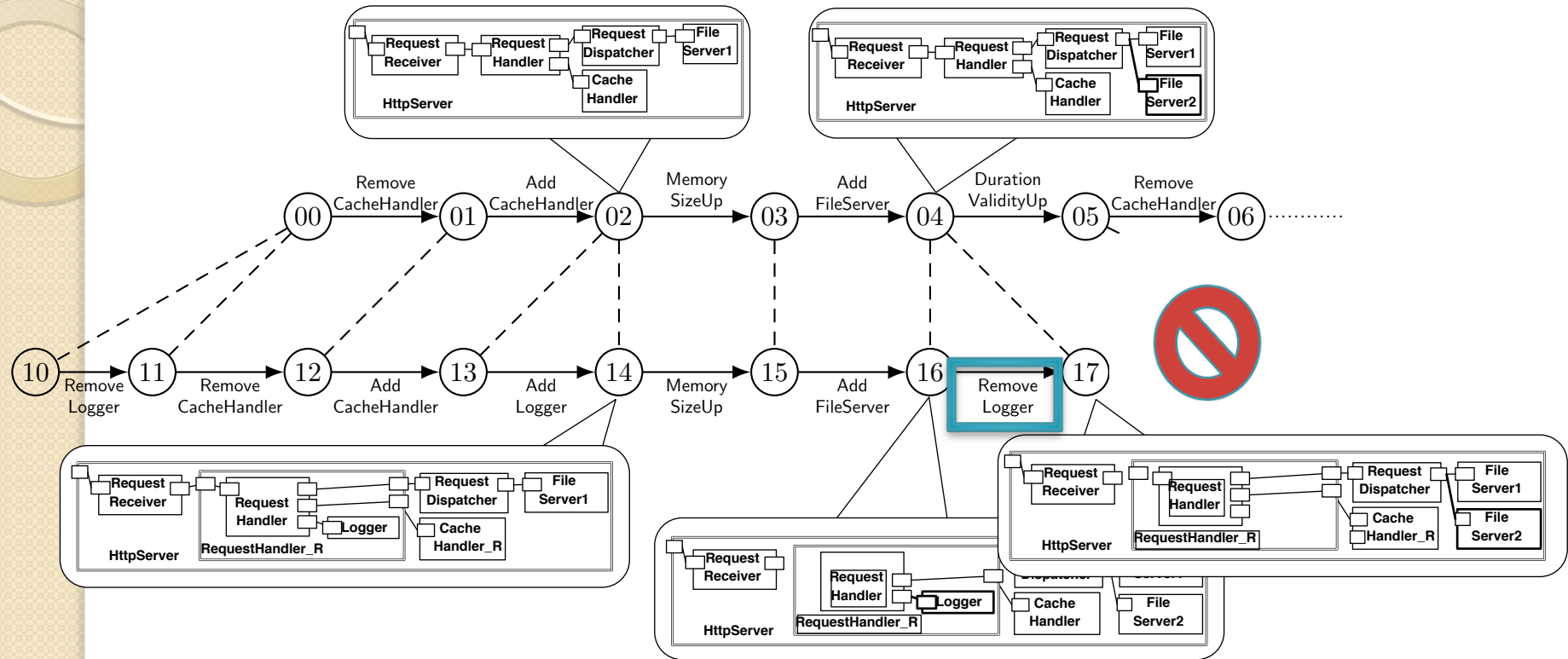
1. Substitutability constraints
2. Strict reconfiguration simulation
3. **Stuttering reconfiguration simulation**

# Substitutability-based simulation



1. Substitutability constraints
2. Strict reconfiguration simulation
3. Stuttering reconfiguration simulation
4. **No cycle of new reconfigurations**

# Substitutability-based simulation



1. Substitutability constraints
2. Strict reconfiguration simulation
3. Stuttering reconfiguration simulation
4. No cycle of new reconfigurations
5. **No new deadlocks**

# Substitutability-based simulation, at runtime

```

1 Data:  $c_R^0 \in \mathcal{C}_R^0, c_A^0 \in \mathcal{C}_A^0, \mathcal{R}_R$  and  $\mathcal{R}_A$ 
2 Result:  $res \in \{\perp, \top^P\}$ , if terminates
3  $c_R \leftarrow c_R^0$ ;
4  $c_A \leftarrow c_A^0$ ;
5 while  $\top$  do
6   if subst( $c_R, c_A$ ) then
7      $\mathcal{E}_R \leftarrow \text{enabled}(c_R, \mathcal{R}_R)$ ;
8      $\mathcal{E}_A \leftarrow \text{enabled}(c_A, \mathcal{R}_A)$ ;
9     if  $\mathcal{E}_R = \emptyset$  then
10      if  $\mathcal{E}_A = \emptyset$  then return  $res \leftarrow \top^P$ ;
11      break ;
12      else return  $res \leftarrow \perp$ ; break ;
13      end if
14    else
15       $ope \leftarrow \text{pick-up}(\mathcal{E}_R)$ ;
16       $c_R \leftarrow \text{apply}(ope, c_R)$ ;
17      if  $ope \in \mathcal{R}_R \setminus \mathcal{R}_A$  then print( $\perp^P$ );
18      else
19        if  $ope \in \mathcal{R}_R \cap \mathcal{R}_A$  and  $ope \in \mathcal{E}_A$ 
20        then
21           $c_A \leftarrow \text{apply}(ope, c_A)$ ;
22          print( $\top^P$ );
23          else return  $res \leftarrow \perp$ ; break ;
24          end if
25        end
26      end
27    else return  $res \leftarrow \perp$ ; break;
28  end if
29 end

```

- A kind of
  - Weak simulation [Milner-Park]
  - Divergence-sensitive stability simulation [van Glabbeek]
- **→ undecidable**, in general

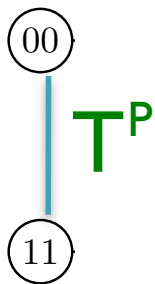
## Runtime evaluation:

$\perp$  { 1. substitutability constraints  
2. strict simulation  
3. stuttering simulation } is broken

$\perp^P$  when **stuttering clause** is correct  
(new reconfigurations **could** introduce potential new cycles, potential new deadlocks)

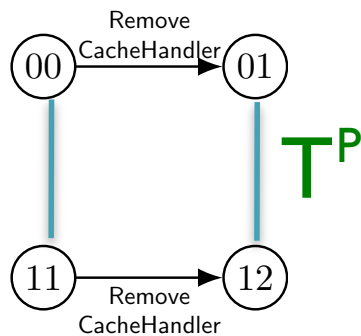
$\top^P$  otherwise  
(the evaluation must be continued...)

# Principle of the runtime evaluation



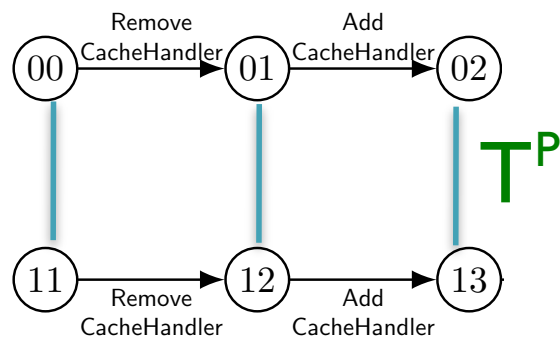
Substitutability constraints?	OK
Strict reconfiguration simulation?	
Stuttering reconfiguration simulation?	
Cycle of new reconfigurations?	
New deadlocks?	

# Principle of the runtime evaluation



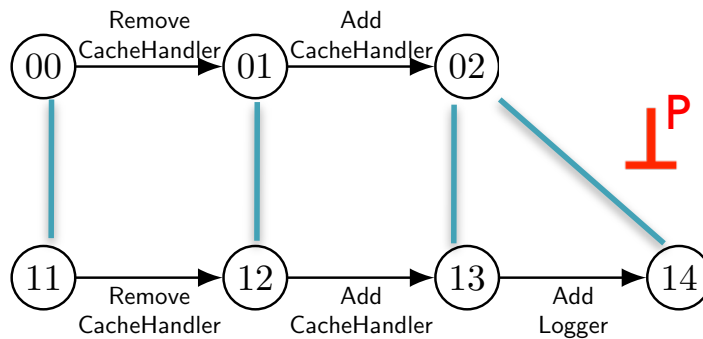
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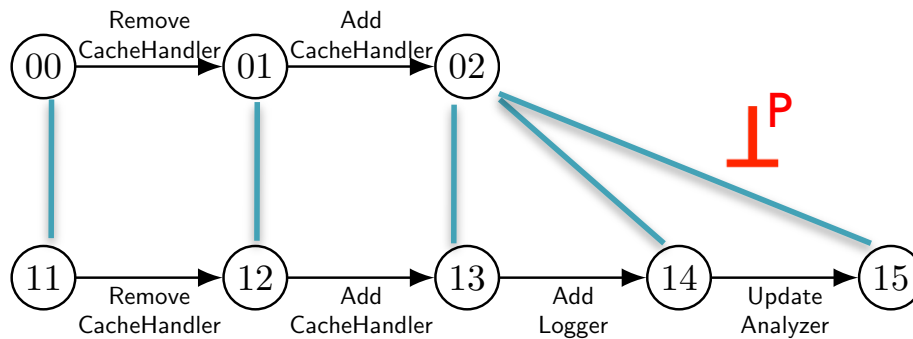
# Principle of the runtime evaluation



Substitutability constraints?	OK
Strict reconfiguration simulation?	
Stuttering reconfiguration simulation?	OK
Cycle of new reconfigurations?	Potentially
New deadlocks?	Potentially

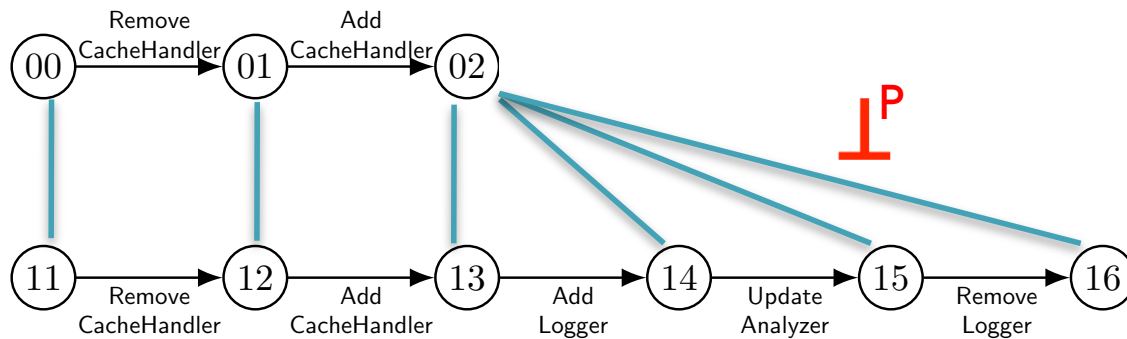


# Principle of the runtime evaluation



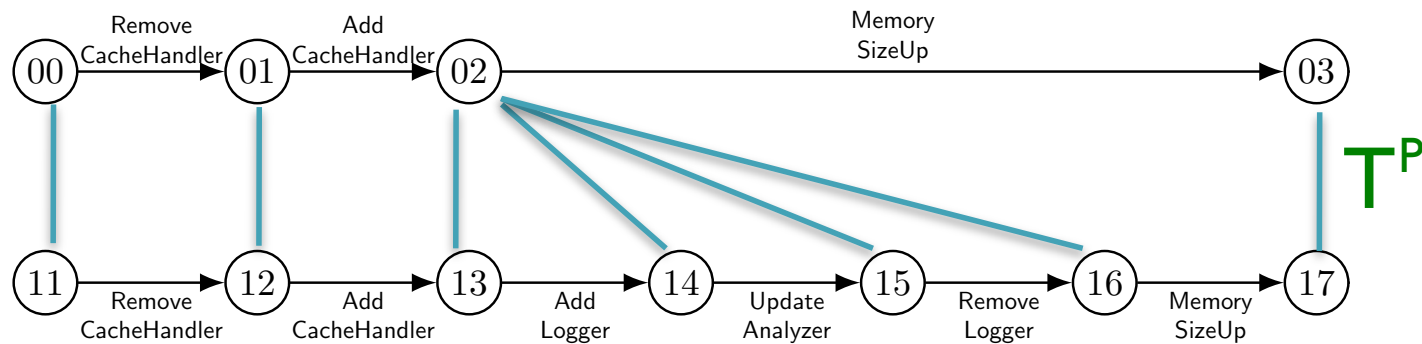
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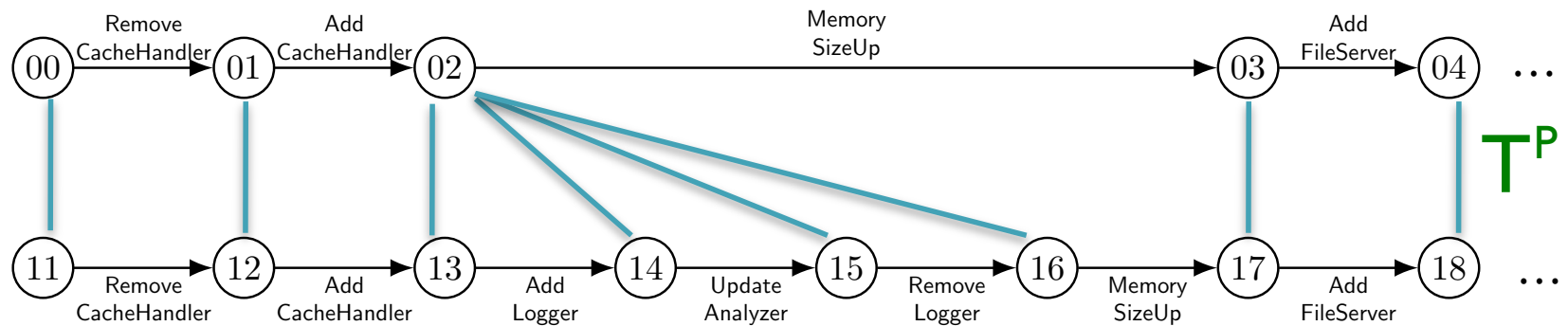
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New deadlocks?	Potentially

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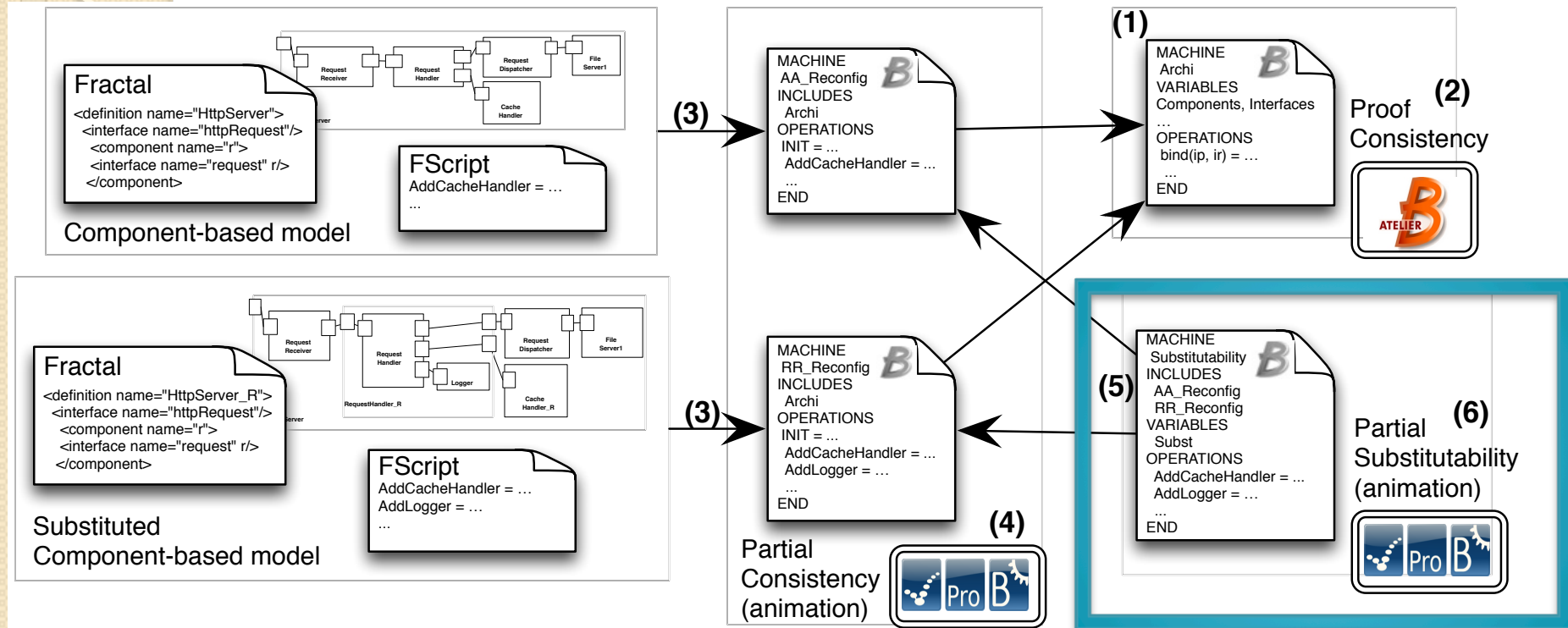
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# Principle of the runtime evaluation



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Strict reconfiguration simulation?	OK
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# Some experimentations





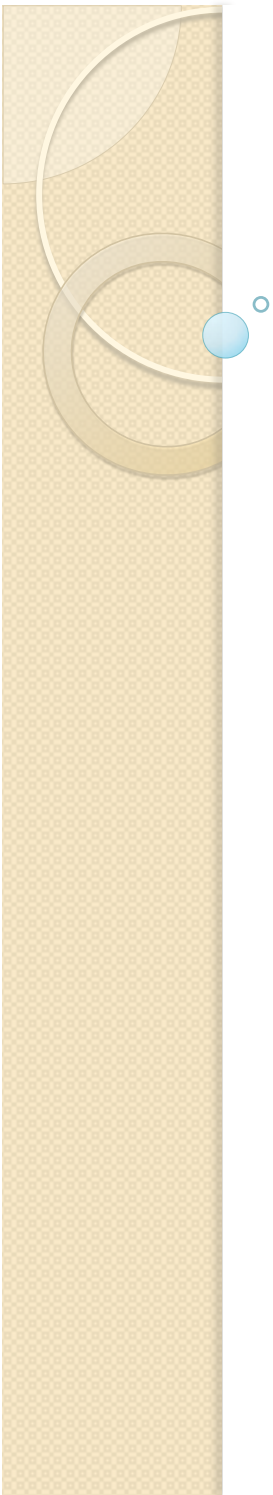
# Conclusion

Component-based model with reconfigurations

Reconfigurations by component substitution

Substitutability-based simulation, at runtime

Implementation with the B-tools



**Thanks for your attention!**