



A Random Testing Approach using Pushdown Automata

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Outline



- 1 Introduction: Random Exploration of Models
- 2 Background on Pushdown Automata
- 3 Algorithms for the Random Generation
- 4 Experimentations
- 5 Conclusion



Random Exploration

Random exploration optimizes the coverage...

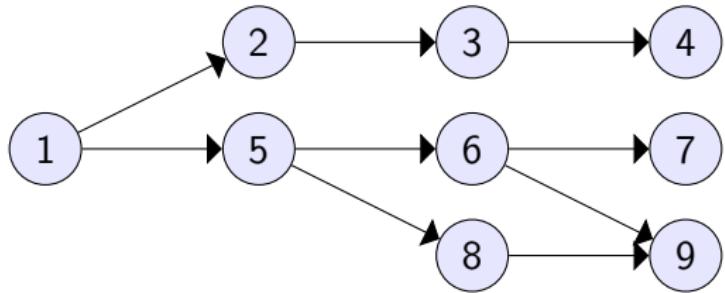
- ▶ Robustness testing, Fuzz testing,
- ▶ Performance testing,
- ▶ Search based testing,
- ▶ Combination of random exploration with other techniques

Combination of graph-based testing and coverage criteria.

Alain Denise, Marie-Claude Gaudel, Sandrine-Dominique Gouraud, Richard Lassaigne, Johan Oudinet, and Sylvain Peyronnet. Coverage-biased random exploration of large models and application to testing. *STTT*, 2012.



Testing on Graphs



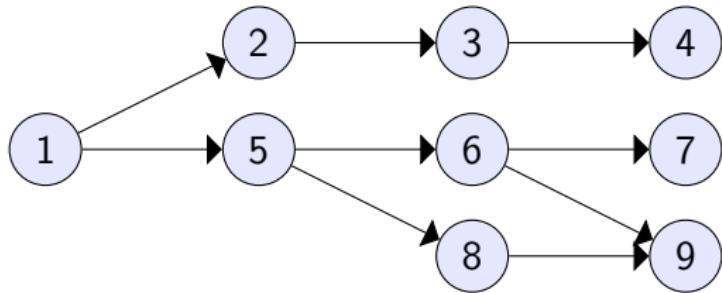
All states,
all transitions,
all loops, etc.

Huge graphs lead to a huge number of tests.

Optimization of the number of tests can be hard (NP-complete).



Testing on Graphs



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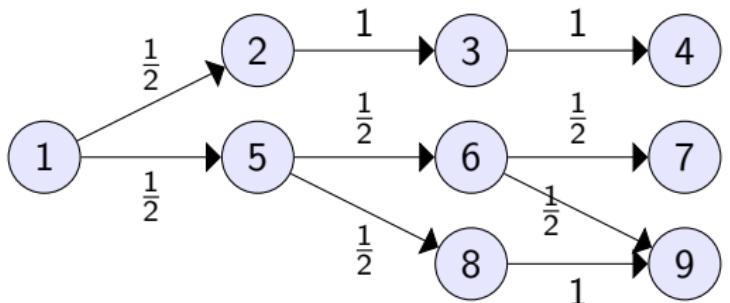
Huge graphs lead to a huge number of tests.

Optimization of the number of tests can be hard (NP-complete).

Reduce the number of tests using a random approach.



Isotropic Random Walks



Paths of length 3.

$1 \rightarrow 2 \rightarrow 3 \rightarrow 4$ probability $\frac{1}{2}$.

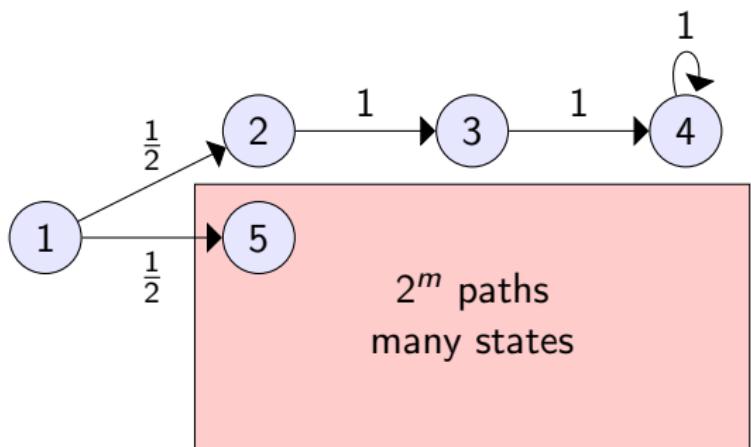
$1 \rightarrow 5 \rightarrow 6 \rightarrow 7$ probability $\frac{1}{8}$.

$1 \rightarrow 5 \rightarrow 6 \rightarrow 9$ probability $\frac{1}{8}$.

$1 \rightarrow 5 \rightarrow 8 \rightarrow 9$ probability $\frac{1}{4}$.

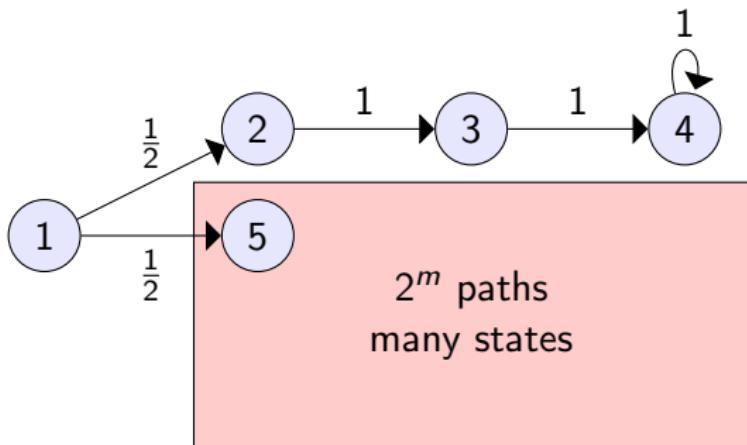


Isotropic Random Walks



$1 \rightarrow 2 \rightarrow 3 \rightarrow 4 \rightarrow \dots \rightarrow 4$ probability $1/2$.
Other paths, probability $1/2^{m+1}$.

Isotropic Random Walks



Over representation
of states 2, 3, 4
and related transitions

Local decisions don't
provide a fair global
coverage.

$1 \rightarrow 2 \rightarrow 3 \rightarrow 4 \rightarrow \dots \rightarrow 4$ probability $1/2$.
Other paths, probability $1/2^{m+1}$.

Uniform Generation of Paths

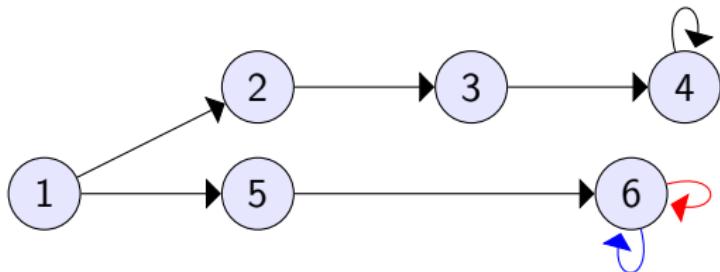


Each path of length n is picked up with the same probability.



Uniform Generation of Paths

Each path of length n is picked up with the same probability.
But some states/transitions can be visited by many paths of length n .



$$\text{Prob. to cover 2: } \frac{1}{1+2^{n-2}}$$

$$\text{Prob. to cover 5: } \frac{2^{n-2}}{1+2^{n-2}}$$

In this case the random walk approach provides a better state coverage.

Quality of the Random Process



Probabilistic quality [T-FW89]

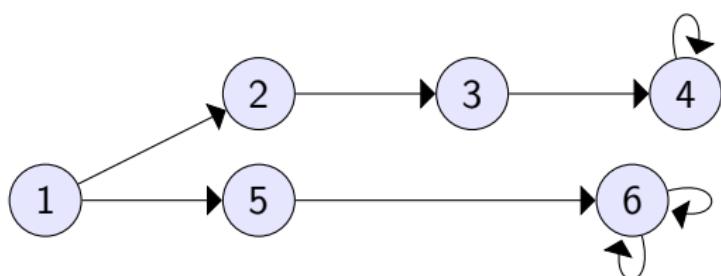
Given a random generation process, its quality $q_{C,N}$, relatively to a coverage criterion C , is the probability that all elements of C are covered when generating N test cases.



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Unif. Gene. Paths.

$$q_{\text{states},N} = 1 - \left(1 - \frac{1}{1+2^{n-2}}\right)^N$$

Not good!

Random Walk

$$q_{\text{states},N} = 1 - \frac{1}{2^N}$$

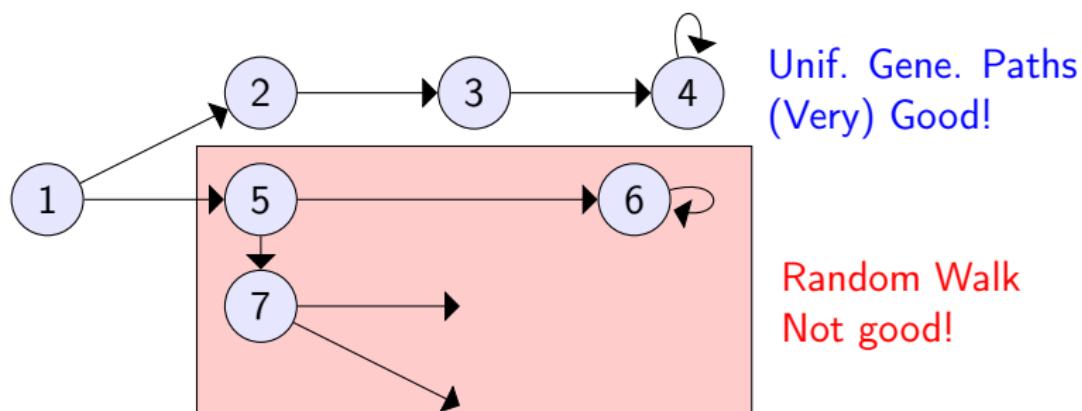
Very good!



Quality of the Random Process

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Random biased Generation

Algorithm [GDG+01]

Repeat N times:

1. Generate $c \in C$ randomly with probability π_c
2. Generate uniformly a path of length n visiting c .

[DGG+12]: how to compute π_c to optimize the quality.

Maximize q_{\min} satisfying

$$\begin{cases} q_{\min} \leq \sum_{c' \in C} \text{prob}(c, c') \pi_c & \text{for all } c \in C \\ \sum_{c \in C} \pi_c = 1 \\ 0 \leq \pi_c \leq 1 & \text{for all } c \in C \end{cases}$$

$\text{prob}(c, c')$: probability that a path of length n visits both c and c' .



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Requirements:

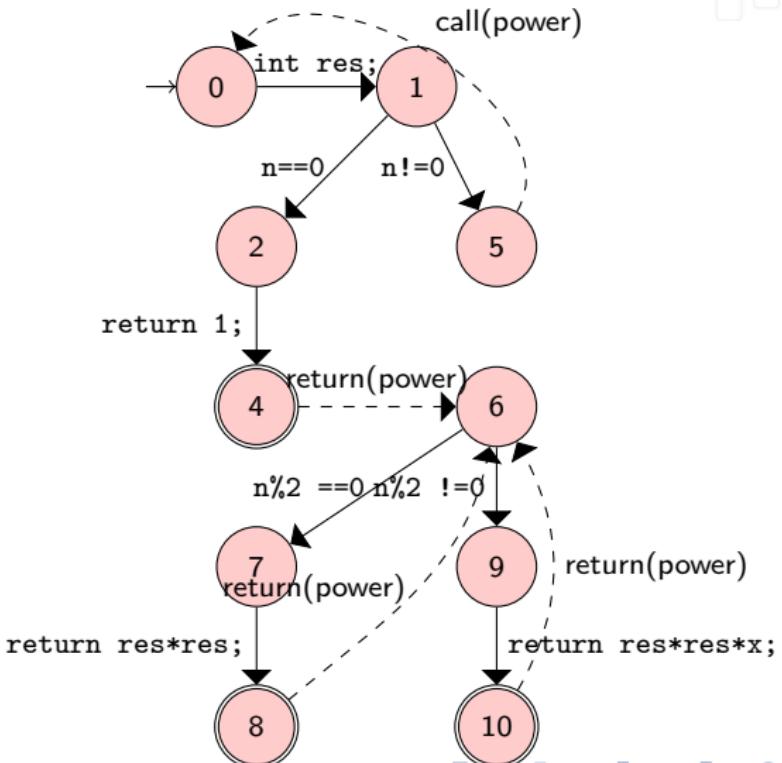
- a. Computing the probability that a path visits both c and c' .
- b. Solving a linear programming problem with $|C|$ variables.
- c. Doing 2.

[DGG+12]: for graphs, for the state coverage criterion.



The Concretization Problem

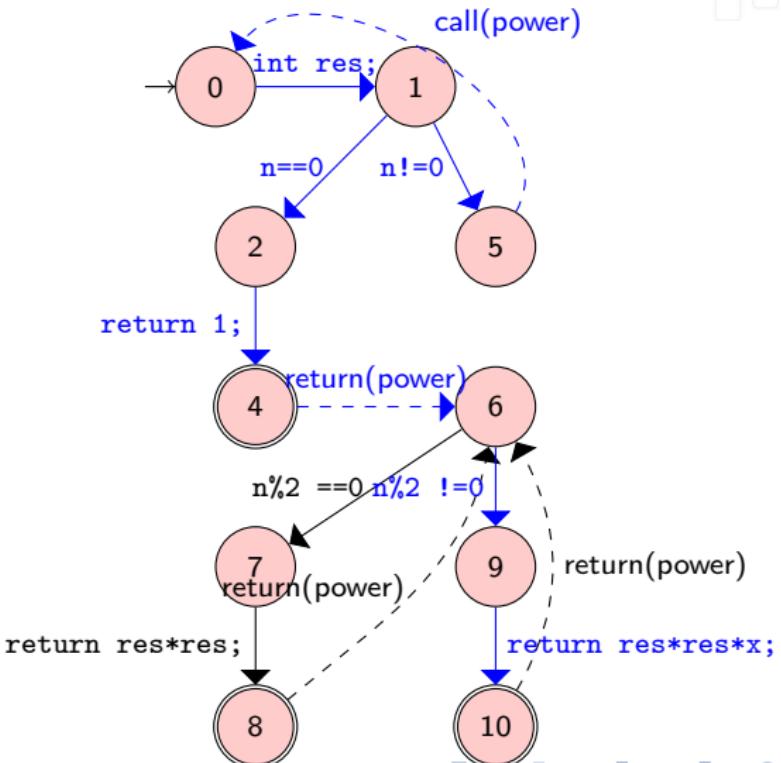
```
int power(float x, int n){  
    int res;  
    if (n==0) {  
        return 1;  
    } else {  
        res = power(x,n/2);  
        if (n%2==0) {  
            return res*res ;  
        } else {  
            return res*res*x  
        }  
    }  
}
```





The Concretization Problem

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        }  
    }  
    power(x,1)
```

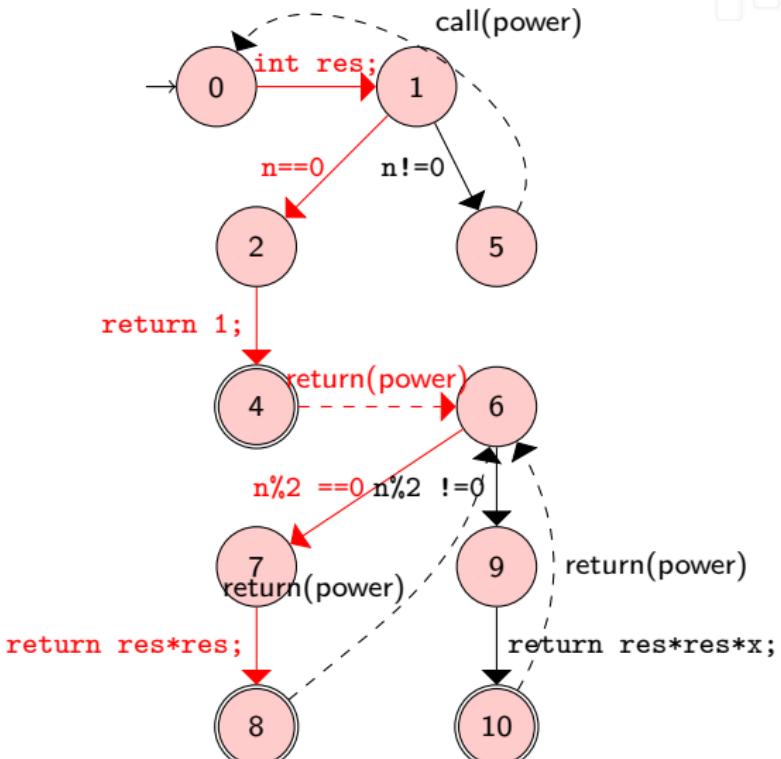




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        }  
    }  
}
```

This path cannot be concretized.





Motivations and Contributions

Main Issue

1. To avoid the concretization problem, use data flow graphs: a huge number of states (billions for simple programs).
2. Random biased approaches require quite small C (and therefore quite small graphs).

Goal

Develop similar techniques for graphs carrying information.

Our Work

Pushdown automata and state/transition coverage criteria.



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Modelling Systems using Pushdown Automata

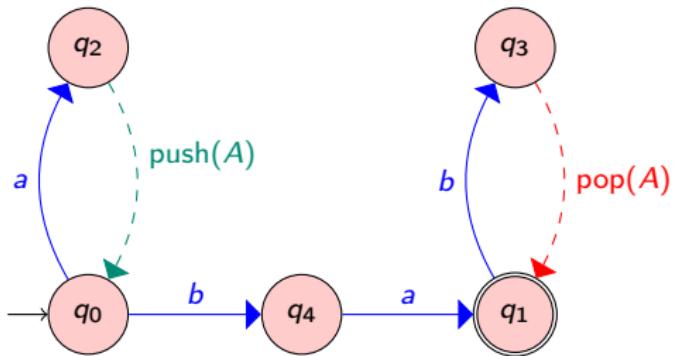


Pushdown automata (PDA)

- ▶ Polynomial time decidability of emptiness, membership,
- ▶ Useful to model systems with (mutually) recursive functions,
- ▶ Useful to model parsing algorithms,
- ▶ Automatic tools to transform Java or C code into pushdown automata,
- ▶ Efficient model-checking tools.



We consider Normalized Deterministic Pushdown Automata.

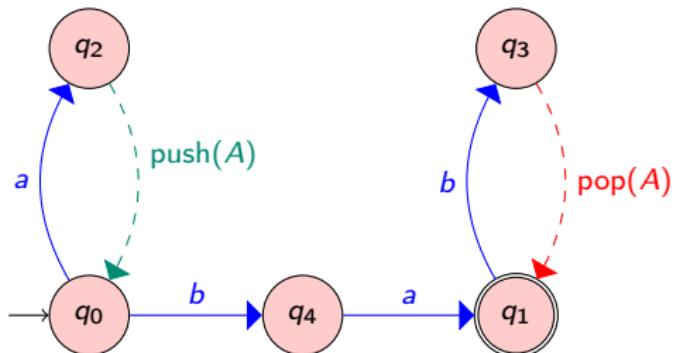


$$\begin{aligned}\Gamma &= \{A\} \text{ (stack)} \\ \Sigma &= \{a, b\} \text{ (actions)} \\ Q &= \{q_0, \dots, q_4\} \text{ (states)} \\ \Delta &= \{(q_0, a, q_2), (q_2, \text{push}(A), q_0), \\ &\quad (q_3, \text{pop}(A), q_1), \dots\} \text{ (transitions)}\end{aligned}$$

Each transition is labelled either by an **action** or a **pop action** or a **push action**.



Configurations in PDA

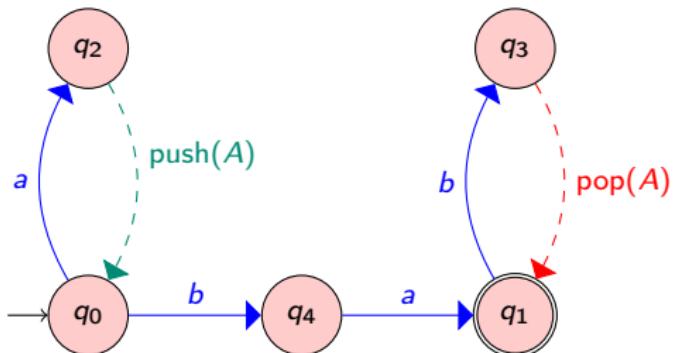


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A *configuration* is a pair (q, w) where $w \in \Gamma^*$. The initial configuration is $(q_{\text{init}}, \varepsilon)$. Final configurations are $(q_{\text{final}}, \varepsilon)$.



Configurations in PDA



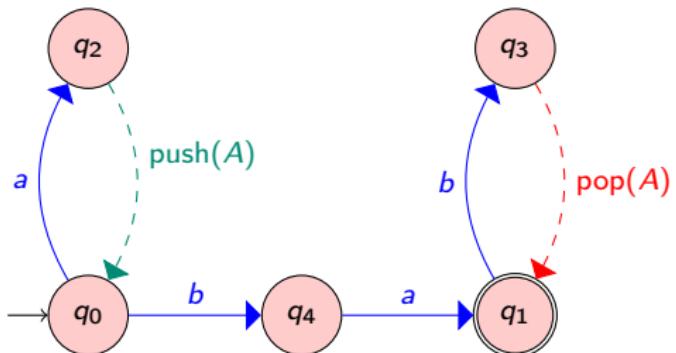
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$(q, w) \xrightarrow{a} (q', w')$ if $(q, a, q') \in \Delta$ and $w = w'$



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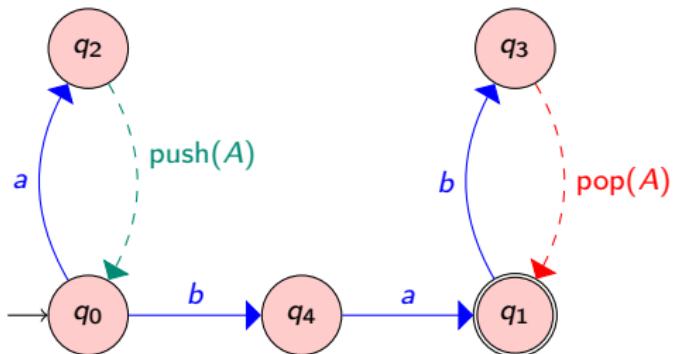
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$(q, w) \xrightarrow{\text{pop}(A)} (q', w')$ if $(q, \text{pop}(A), q') \in \Delta$ and $w = w'A$



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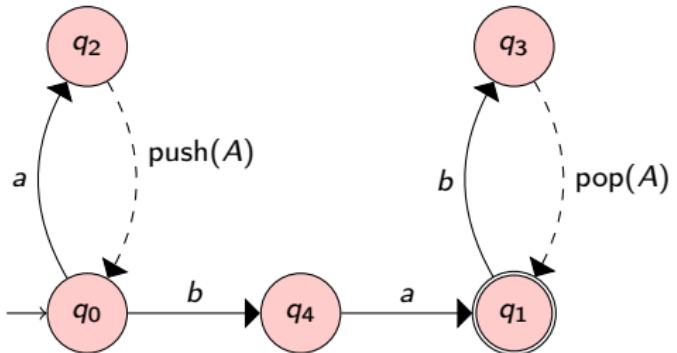
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$(q, w) \xrightarrow{\text{push}(A)} (q', w')$ if $(q, \text{push}(A), q') \in \Delta$ and $wA = w'$



Successful PDA-paths



$$\begin{aligned}\Gamma &= \{A\} \text{ (stack)} \\ \Sigma &= \{a, b\} \text{ (actions)} \\ Q &= \{q_0, \dots, q_4\} \text{ (states)} \\ \Delta &= \{(q_0, a, q_2), (q_2, \text{push}(A), q_0), \\ &\quad (q_3, \text{pop}(A), q_1), \dots\} \text{ (transitions)}\end{aligned}$$

A *successful PDA-path* is a sequence of configurations linked by transitions, with initial and final conditions.

$$(q_0, \varepsilon) \xrightarrow{a} (q_2, \varepsilon) \xrightarrow{\text{push}(A)} (q_0, A) \xrightarrow{b} (q_4, A) \xrightarrow{a} (q_1, A) \xrightarrow{b} (q_3, A) \xrightarrow{\text{pop}(A)} (q_1, \varepsilon)$$

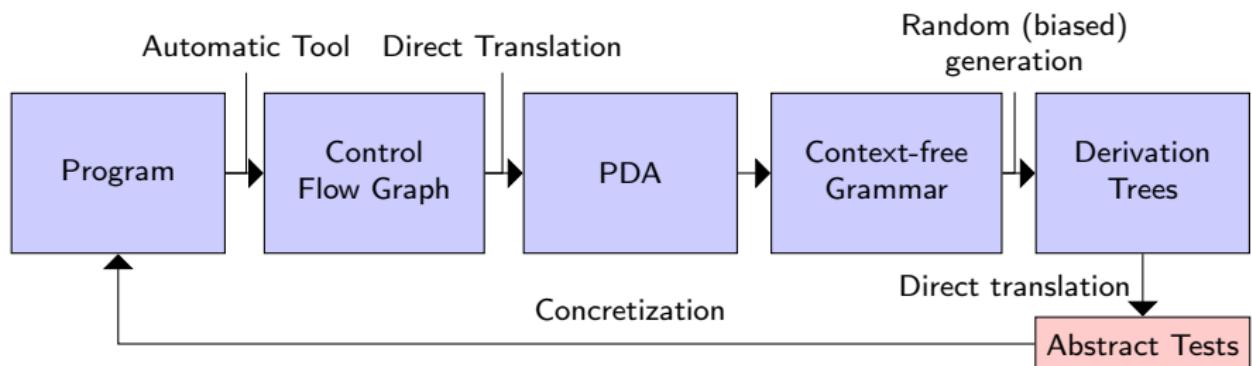
Given a path of length $4n + 2$ in the graph from q_0 to q_1 , the probability that it corresponds to a successful PDA-path is $\frac{1}{2n+1}$.



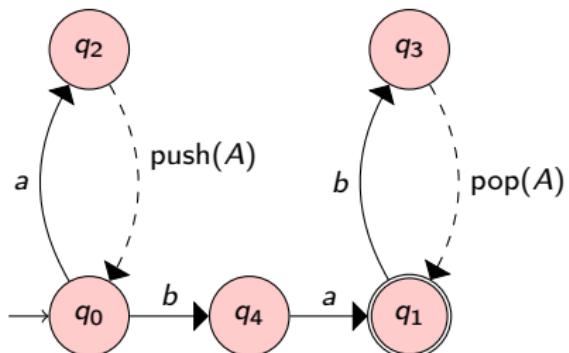
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Overview of the Approach (Doing 2.)



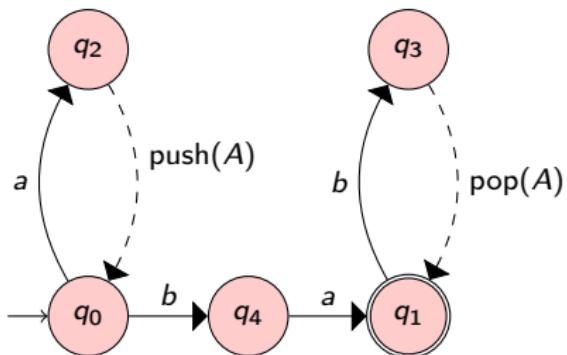
From Pushdown Automata to Grammars





From Pushdown Automata to Grammars

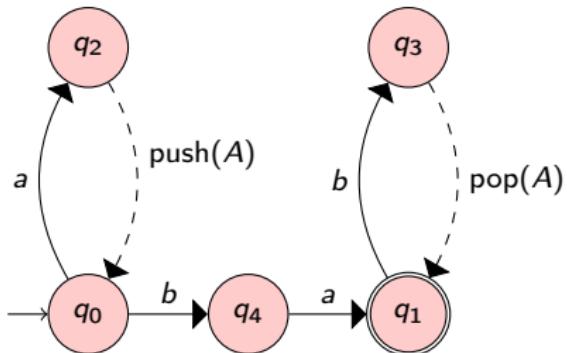
One can compute a grammar generating successful paths.



$$\begin{aligned}X_0 &\rightarrow (q_0, a, q_2) X_2 \mid (q_0, b, q_4) (q_4, a, q_2) \\X_2 &\rightarrow (q_2, \text{push}(A), q_0) X_0 S \\S &\rightarrow (q_1, b, q_3) (q_3, \text{pop}(A), q_1)\end{aligned}$$

From Pushdown Automata to Grammars

One can compute a grammar generating successful paths.



$$\begin{aligned} X_0 &\rightarrow (q_0, a, q_2)X_2 \mid (q_0, b, q_4)(q_4, a, q_2) \\ X_2 &\rightarrow (q_2, \text{push}(A), q_0)X_0S \\ S &\rightarrow (q_1, b, q_3)(q_3, \text{pop}(A), q_1) \end{aligned}$$

Bijection Paths/D. Trees.

$$\begin{aligned} X_0 &\rightarrow (q_0, a, q_2)X_2 \rightarrow (q_0, a, q_2)(q_2, \text{push}(A), q_0)X_0S \\ &\rightarrow^* [(q_0, a, q_2)(q_2, \text{push}(A), q_0)]^2 X_0SS \\ &\rightarrow [(q_0, a, q_2)(q_2, \text{push}(A), q_0)]^2 (q_0, b, q_4)(q_4, a, q_2)SS \\ &\rightarrow^* [(q_0, a, q_2)(q_2, \text{push}(A), q_0)]^2 (q_0, b, q_4)(q_4, a, q_2)[(q_1, b, q_3)(q_3, \text{pop}(A), q_1)]^2 \end{aligned}$$



A Counting Approach [NW78][FZC94]

Example (a, b, c, d are terminal symbols):

$$E := EcE \mid EEd \mid a \mid b$$

The size of a derivation tree is its number of leaves.

- ▶ c_n number of trees of size n whose root rule is $E \rightarrow EcE$.
- ▶ d_n number of trees of size n whose root rule is $E \rightarrow EEd$.
- ▶ a_n number of trees of size n whose root rule is $E \rightarrow a$.
- ▶ b_n number of trees of size n whose root rule is $E \rightarrow b$.
- ▶ v_n number of trees of size n , $v_n = a_n + b_n + c_n + d_n$.

One has

- ▶ $v_1 = 2$, $v_2 = 0$ and $v_3 = 8$ $(a|b)c(a|b)$ and $(a|b)(a|b)d$.
- ▶ For example,

$$c_n = \sum_{k=1}^{n-1} v_k v_{n-k-1}.$$

- ▶ v_n , a_n , b_n , c_n and d_n can be computed recursively.

Random Generation of Trees [NW78][FZC94]

$$E := EcE \mid EEd \mid a \mid b$$

To generate derivation trees of size n .

Random Generation of Trees [NW78][FZC94]



$E := EcE \mid EEd \mid a \mid b$ To generate derivation trees of size n .

1. Compute a_k, d_k, b_k, c_k, v_k for all $k \leq n$.

Random Generation of Trees [NW78][FZC94]

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To generate derivation trees of size n .

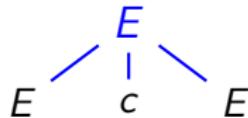
1. Compute a_k, d_k, b_k, c_k, v_k for all $k \leq n$.
2. Root rule is

$E \rightarrow EcE$ with probability $\frac{c_n}{v_n}$,

$E \rightarrow EEd$ with probability $\frac{d_n}{v_n}$,

$E \rightarrow a$ with probability $\frac{a_n}{v_n}$ and

$E \rightarrow b$ with probability $\frac{b_n}{v_n}$.



Random Generation of Trees [NW78][FZC94]

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To generate derivation trees of size n .

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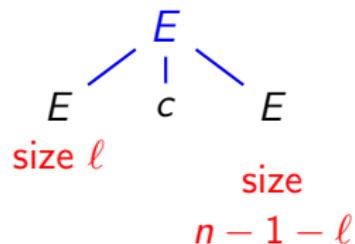
$E \rightarrow EEd$ with probability $\frac{d_n}{v_n}$,

$E \rightarrow a$ with probability $\frac{a_n}{v_n}$ and

$E \rightarrow b$ with probability $\frac{b_n}{v_n}$.

3. Left child has size ℓ with probability

$$\frac{v_\ell v_{n-1-\ell}}{c_n}.$$



Note that v_n is the number of PDA-paths of length n .

Random Generation of Trees [NW78][FZC94]

$$E := EcE \mid EEd \mid a \mid b$$

To generate derivation trees of size n .

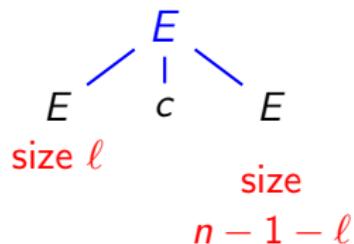
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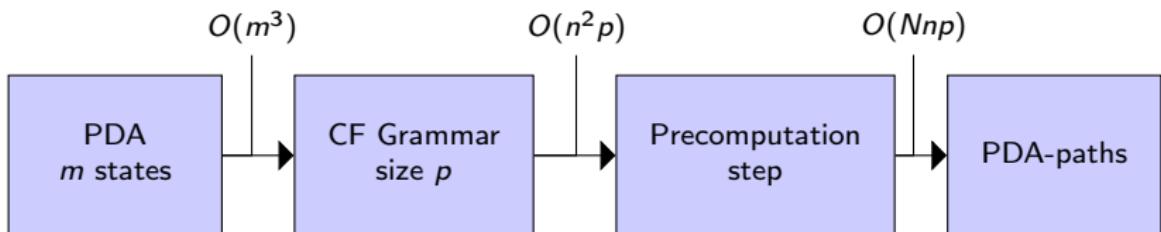
3. Left child has size ℓ with probability $\frac{v_\ell v_{n-1-\ell}}{c_n}$.
4. Recursive generation.

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Complexity



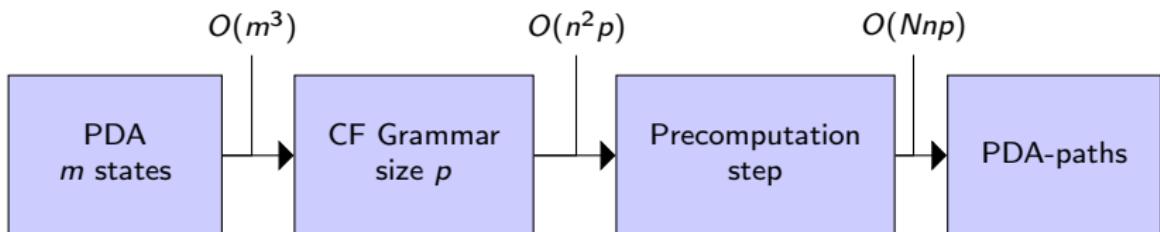
Generation of N PDA-paths of length n .



Complexity



Generation of N PDA-paths of length n .



Cleaning step



Random biased Generation (Reminder)

Algorithm [GDG+01]

Repeat N times:

1. Generate $c \in C$ randomly with probability π_c
2. Generate uniformly a path of length n visiting c .

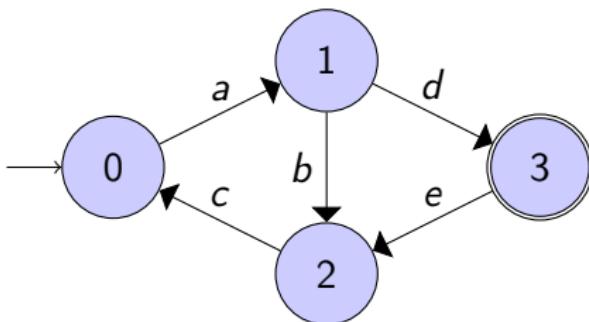
[DGG+12]: how to compute π_c to optimize the quality.

Requirements:

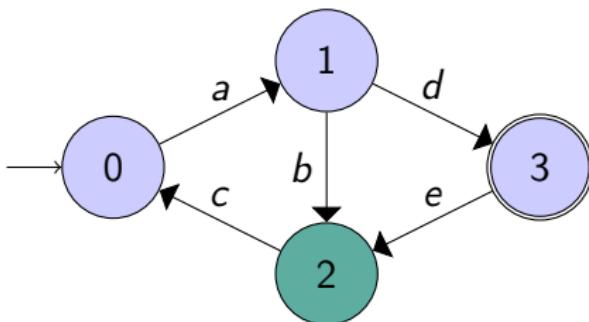
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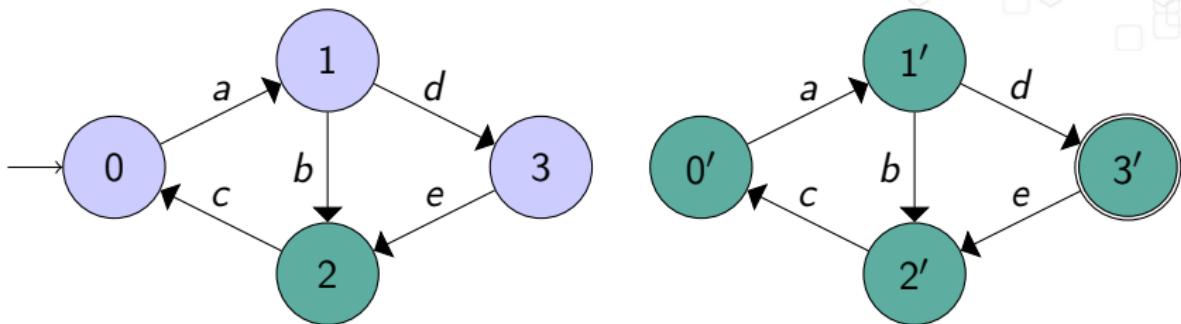
Random biased Generation for States



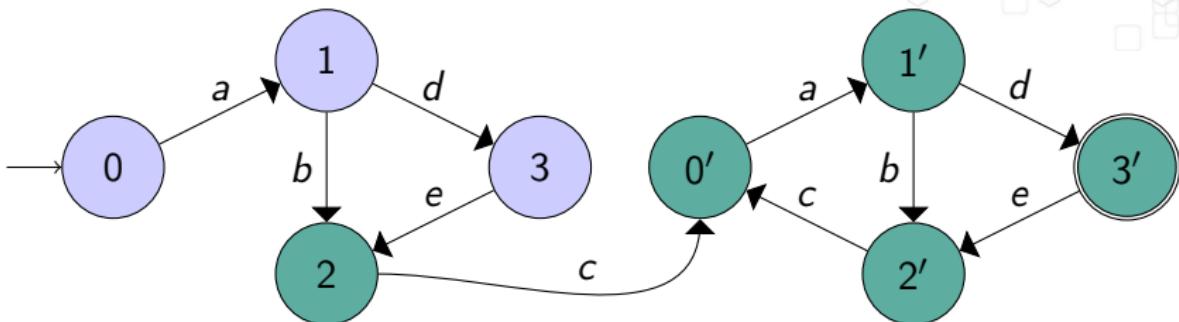
Random biased Generation for States



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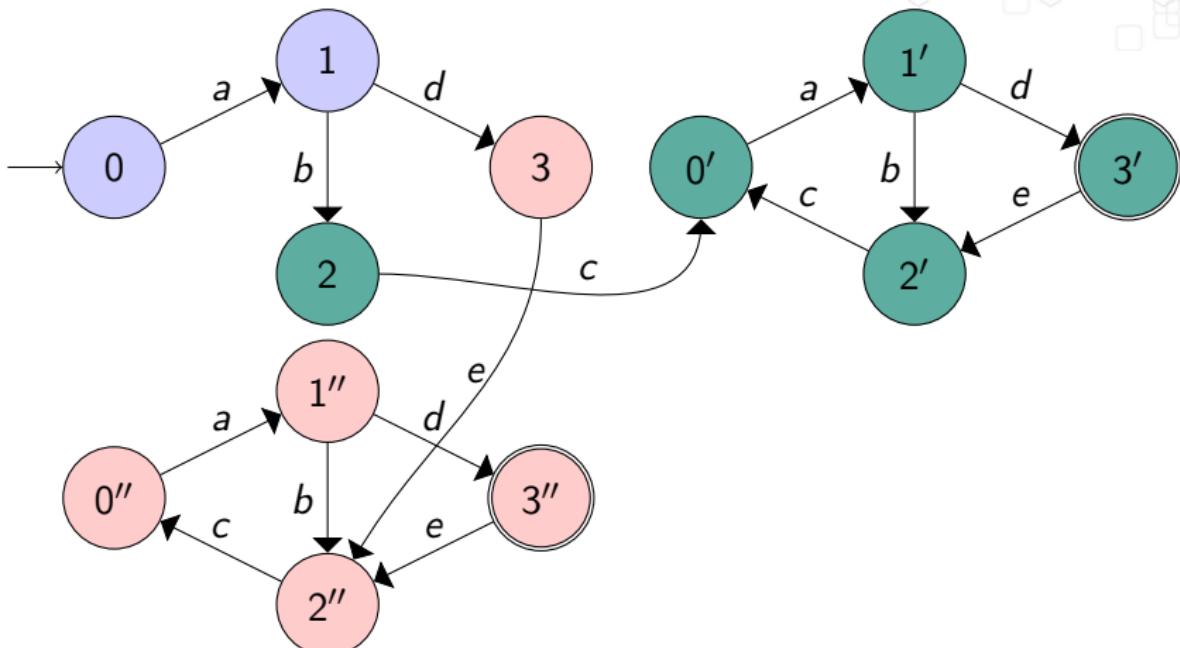


Random biased Generation for States



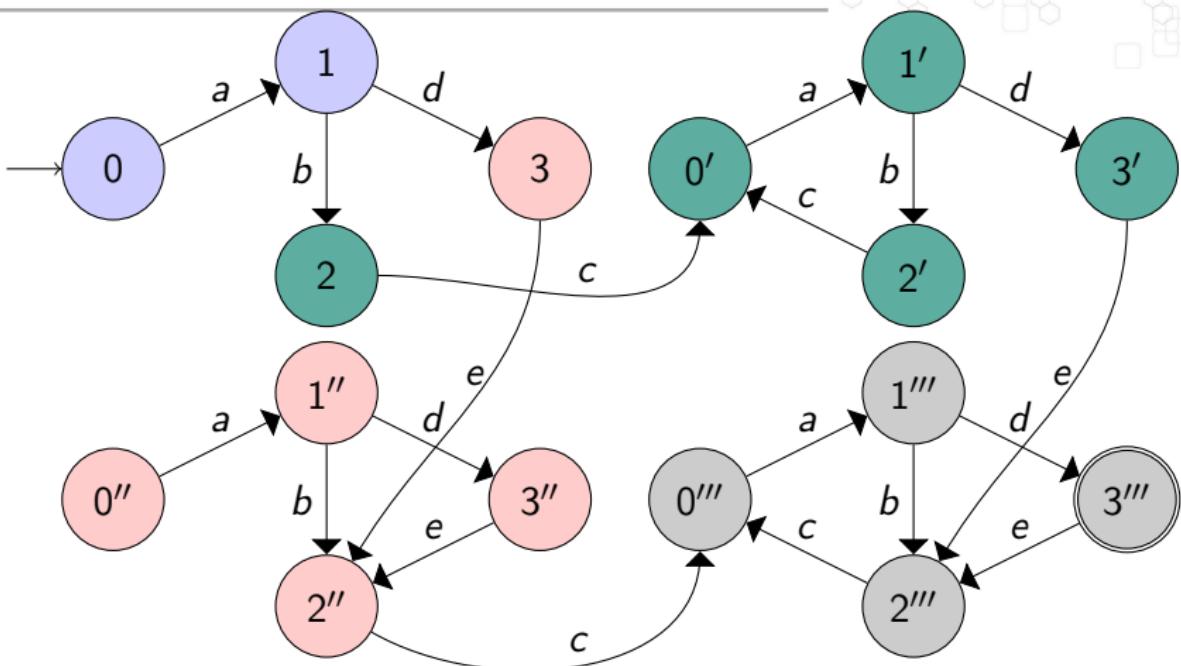
Allows the generation (and the enumeration) of paths of length n visiting 2.

Random biased Generation for States



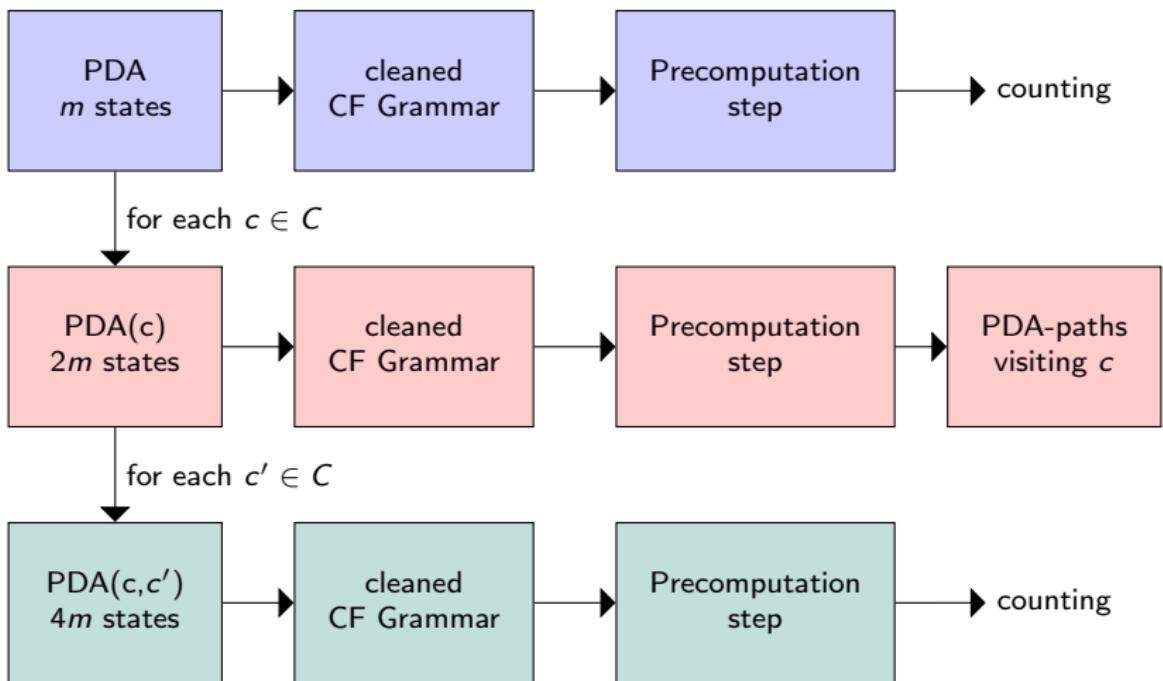
Allows the generation (and the enumeration) of paths of length n visiting 2 or 3.

Random biased Generation for States



Allows the generation (and the enumeration) of paths of length n visiting 2 and 3. Similar construction for transitions.

Overview





Using Coverage Criteria

Algorithm 1

Randomly and uniformly generates PDA-paths until C is covered.

Algorithm 2

Randomly and uniformly generates a PDA-path visiting a non already covered element until C is covered.

Algorithm 3

Randomly generates a PDA-paths with optimized probabilities element until C is covered.

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Examples, Shunting Yard Algorithm

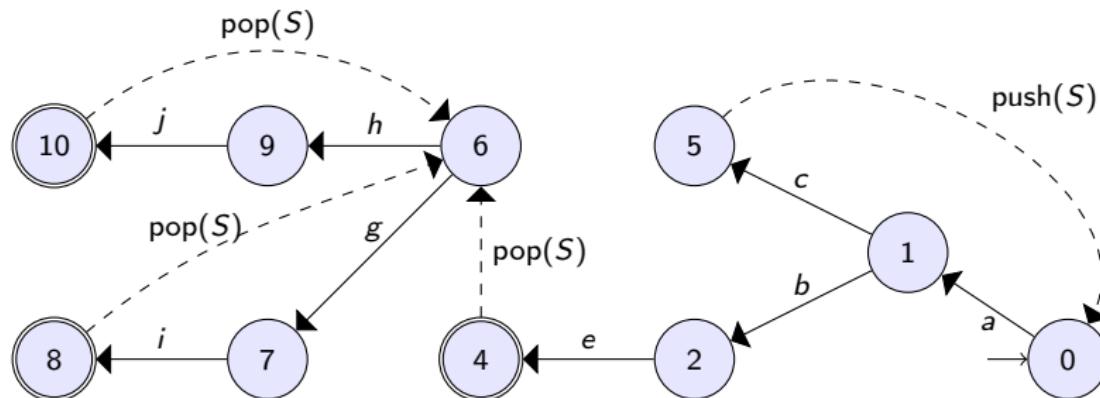


Algorithm to translate an arithmetic expression into the equivalent expression in the Reverse Polish notation.

$$(3 + 2) * (5 + 4) \rightarrow 3\ 2\ +\ 5\ 4\ +\ *$$

The algorithm exploits a stack data structure.

Examples, the Power Function



Corresponding to the control flow graph of function computing x^k .

Examples, the Modulo Function

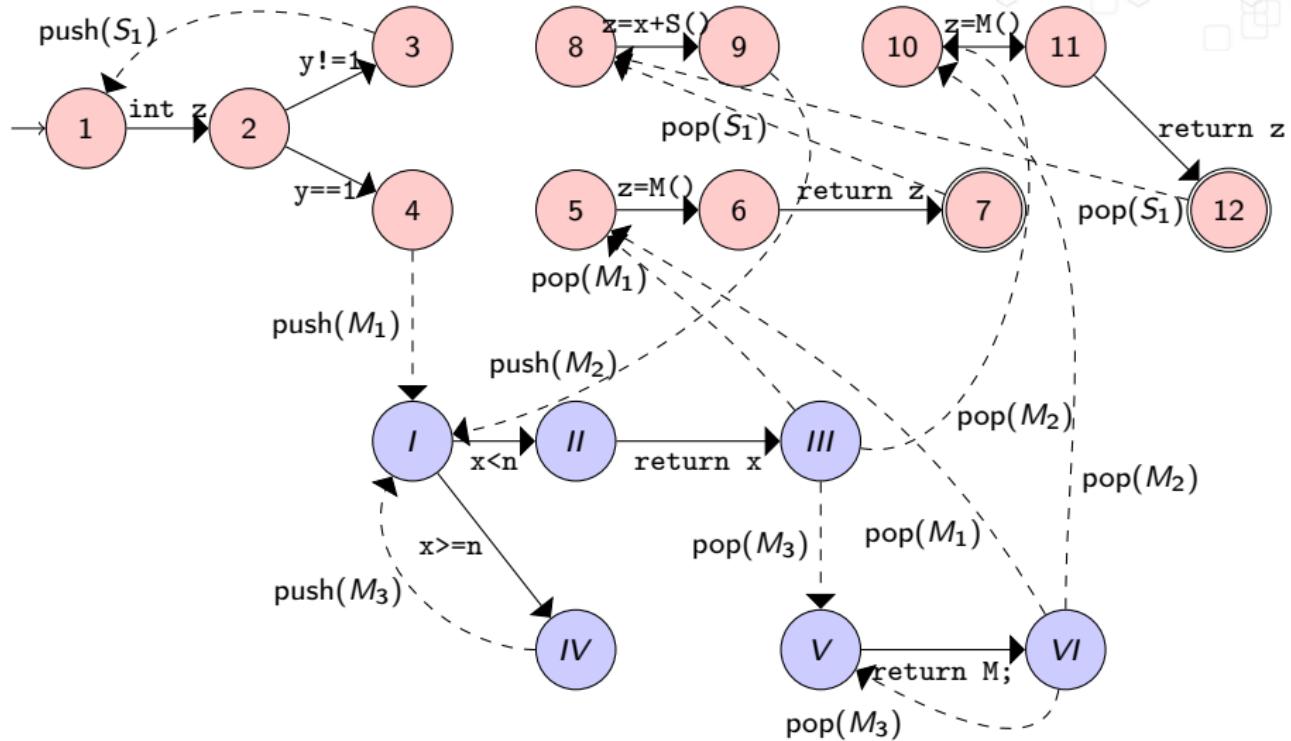


$M(x, n) = x \text{ modulo } n$ and $S(x, y, n) = x * y \text{ modulo } n$

```
int S(int x, int y, int
n){
    int z;
    if (y == 1){
        z = M(x,n);
        return z;
    } else {
        z = x +
S(x,y-1,n);
        z = M(z,n);
        return z;
    }
}
```

```
int M(int x, int n){
    if (x < 1){
        return x;
    } else {
        return M(x-n,n);
    }
}
```

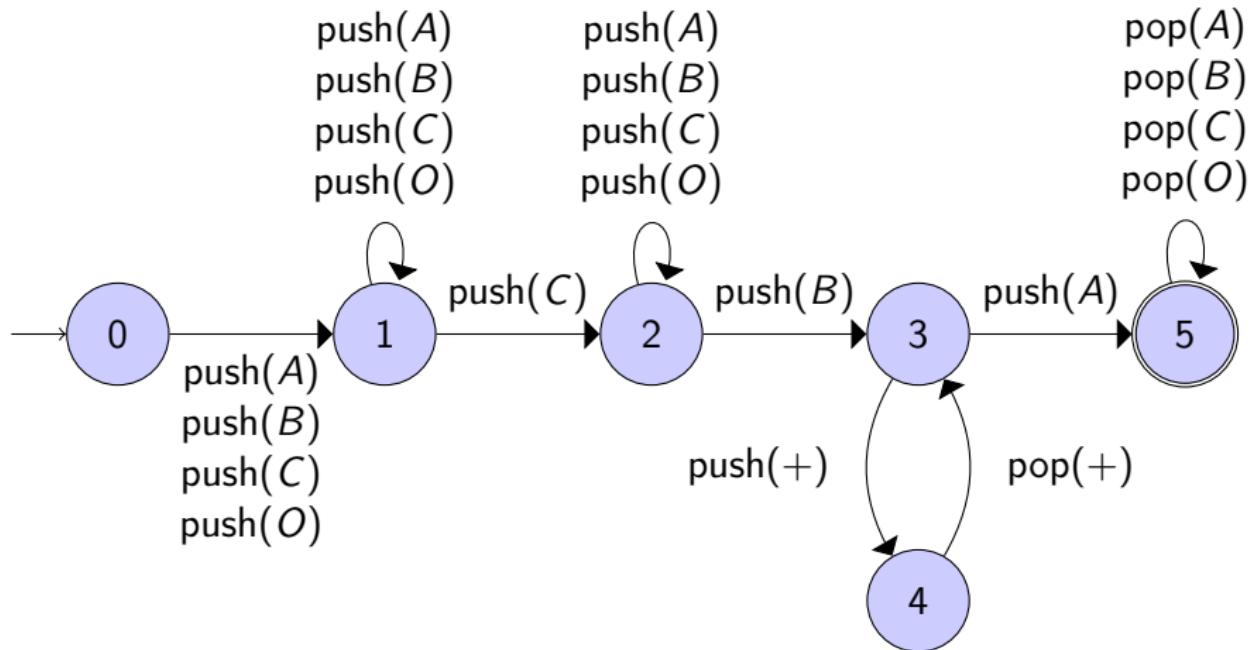
Examples, the Modulo Function



Examples, XPATH Query



Modeling an XPATH query (from [C08]).



Examples, Sizes of the PDA



	states	transitions (1)	transitions (2)
Shunting Yard	23	36	102
Power	10	12	24
Modulo	18	24	90
XPATH	6	21	102

- (1) Normalized transitions
- (2) Considering all transitions

Sizes of the examples are comparable to those obtained by the automatic transformation into pushdown models of some industrial drivers [ST12].

NPDA vs. Finite Automata: $\mathcal{A}_{\text{modulo}}$



Path size	Our approach	Approach of [DGG+12]
from 1 to 7	no NPDA-trace	no DFA-trace
8	1-2-4-I-II-III-5-6-7 (10)	1-2-4-I-II-III-5-6-7 (4) 1-2-4-I-II-III-10-11-12 (6)
9	no NPDA-trace	no DFA-trace
10	no NPDA-trace	1-2-4-I-IV-I-II-III-5-6-7 (3) 1-2-4-I-IV-I-II-III-10-11-12 (2) 1-2-4-I-II-III-V-VI-10-11-12 (3) 1-2-4-I-II-III-V-VI-5-6-7 (2)
11	no NPDA-trace	A-2-3-1-2-4-I-II-III-10-11-12 (6) 1-2-31-2-4-I-II-III-5-6-7 (4)

NPDA vs. Finite Automata: A_{modulo}

n	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26
NPDA	1	0	0	0	1	0	0	1	1	0	0	1	1	0	0
DFA	6	4	10	6	18	10	34	18	64	34	114	64	200	114	356

n	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41
NPDA	3	1	0	1	4	1	0	3	5	1	0	0	0	0	142
DFA	200	640	356	1152	640	2066	1152	3692	2066	6598	3692	2.4 10 ⁹			

For several lengths, as 21, 29, 37, there is no NPDA-traces. All generated DFA-traces would be not consistent.

Mutant based Evaluation



Using the PDA model of the Shunting Yard Algorithm and its implementation (from Wikipedia).

Uniform random generation of PDA-paths of length n .

Number of required test cases (20 experiments for each case).

	Killing mutants			Covering transitions			Cov. 79% of the code		
n	min	max	aver.	min	max	aver.	min	max	aver.
10	2	16	7.8	7	48	15.3	3	17	6.9
15	1	7	3.7	4	19	8.8	2	7	4.5
20	2	11	3.2	3	10	5.4	2	6	2.9

10 different mutants used: 4 Inc./Dec., 1 Arr. Ref. Replacement, 1 Switch Statement Mut., 4 Log. Neg.

Uniform Random Generation



	Grammar Size	Grammar Gen. Time(s)	Cleaned Grammar	Grammar Cleaning Time(s)	Precomp. Time(s)	100 Paths Gen. Time (s)
\mathcal{A}_{xpath}	217+ 3463	0.03	27+87	0.38	(10) 0.07 (20) 0.22 (30) 0.57 (100) 17.21 (200) 141	(10) 0.09 (20) 0.17 (30) 0.63 (100) 1.1 (200) 2.83
\mathcal{A}_{power}	201+369	0.02	27+31	0.05	(100) 0.98 (200) 5.63 (500) 78.96	(100) 0.41 (196) 0.94 (496) 3.94
\mathcal{A}_{modulo}	1621+ 7572	0.07	45+50	6.07	(10) 0.03 (20) 0.08 (50) 0.41 (100) 2.29 (200) 14.86	(8) 0.07 (21) 0.14 (49) 0.32 (99) 0.28 (199) 1.4
\mathcal{A}_{SY}	1937+ 16735	0.13	143+ 261	16.61	(10) 0.16 (20) 0.58 (30) 1.46 (100) 39.21 (200) 326.28	(10) 0.13 (20) 0.24 (30) 0.34 (100) 1.14 (200) 2.35

Using Coverage Criteria



Algorithm 1

Randomly and uniformly generates PDA-paths until C is covered.

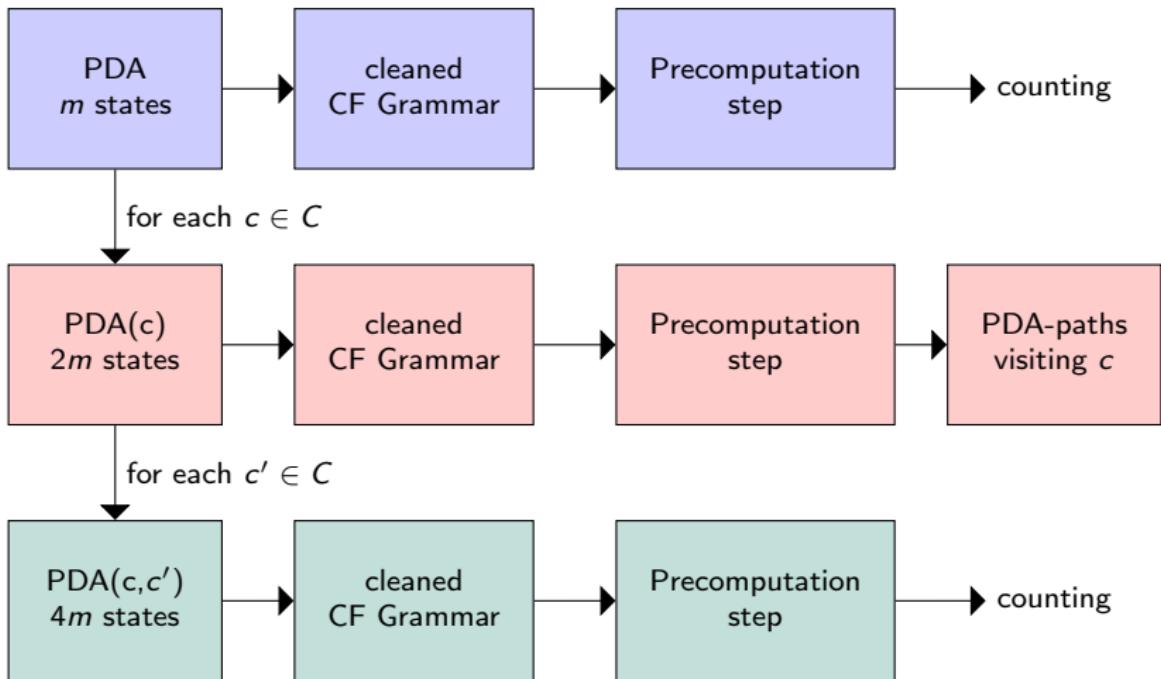
Algorithm 2

Randomly and uniformly generates a PDA-path visiting a non already covered element until C is covered.

Algorithm 3

Randomly generates a PDA-paths with optimized probabilities element until C is covered.

Overview



Computation time for Algorithm 2/3



From cleaned grammars: Computation time for

- 1) generating paths of length 60 visiting a given state/transition,
and
- 2) computing their probabilities.

	\mathcal{A}_{xpath}	\mathcal{A}_{power}	\mathcal{A}_{modulo}	\mathcal{A}_{SY}
total time (state)	38s	5.25s	22min	136min
av. grammar size	31.3+98.8	32.2+36.8	65.2+72.9	342.7+692.9
total time (transition)	91s	6.3s	33min	219min
av. grammar sizes	30.5+94.8	30.7+34.3	66.2+73.7	273.3+572.6



Computation time for Algorithm 3

Computation time of the linear programming systems.

	\mathcal{A}_{xpath}	\mathcal{A}_{power}	\mathcal{A}_{modulo}	\mathcal{A}_{SY}
av. time (one pair of states)	13.4s	0.9s	408s	110min
total (state)	7min19s	79s	34h12min	847h (*)
total (transition)	25min	81s	60h39min	1200h (*)
total (simplified, state)	1min	insign.	9h (*)	120h (*)
total (simplified, transition)	8min (*)	insign.	18h (*)	350h (*)

(*) estimated time.

Simplifications based on symmetry/replication.

Comparing Algorithms for $\mathcal{A}_{\text{xpath}}$



Average number of paths for several lengths, to cover either all states or all transitions.

n	12	14	16	18	20	22	24	26	28	30	32
Algo. 1	7.51	6.1	5.0	4.77	4.74	4.24	4.43	4.37	4.34	4.34	4.33
Algo. 2	1.87	1.84	1.83	1.77	1.8	1.78	1.79	1.77	1.77	1.76	1.77
Algo. 3	1	1	1	1	1	1	1	1	1	1	1
Algo. 1	14.1	11.03	10.08	9.27	8.83	9.06	8.64	9.36	9.45	8.59	9.43
Algo. 2	6.9	6.07	5.57	5.08	4.92	4.68	4.66	4.71	4.51	4.52	4.51
Algo. 3	14.1	-	-	9.1	-	-	-	-	8.8	-	-

- Performing 100 experiments
- Comparing theoretical and experimental results

Outline



- 1 Introduction: Random Exploration of Models
- 2 Background on Pushdown Automata
- 3 Algorithms for the Random Generation
- 4 Experimentations
- 5 Conclusion

Conclusion and Future Work



On computation times

1. Results obtained using a Python based prototype,
2. Many possible optimizations,
3. Can easily be distributed.

Conclusion

- ▶ Algorithms 1 and 2 are tractable.
- ▶ Challenging results.
- ▶ Algorithm 3 requires more investigations to handle large examples.

Future Work



Perspectives

- ▶ Look for Algorithm 3 optimizations,
- ▶ Develop an optimized tool,
- ▶ Develop efficient algorithms for cleaning the grammar,
- ▶ Develop similar approaches for other classes of automata
(counter automata, timed automata, ...)